

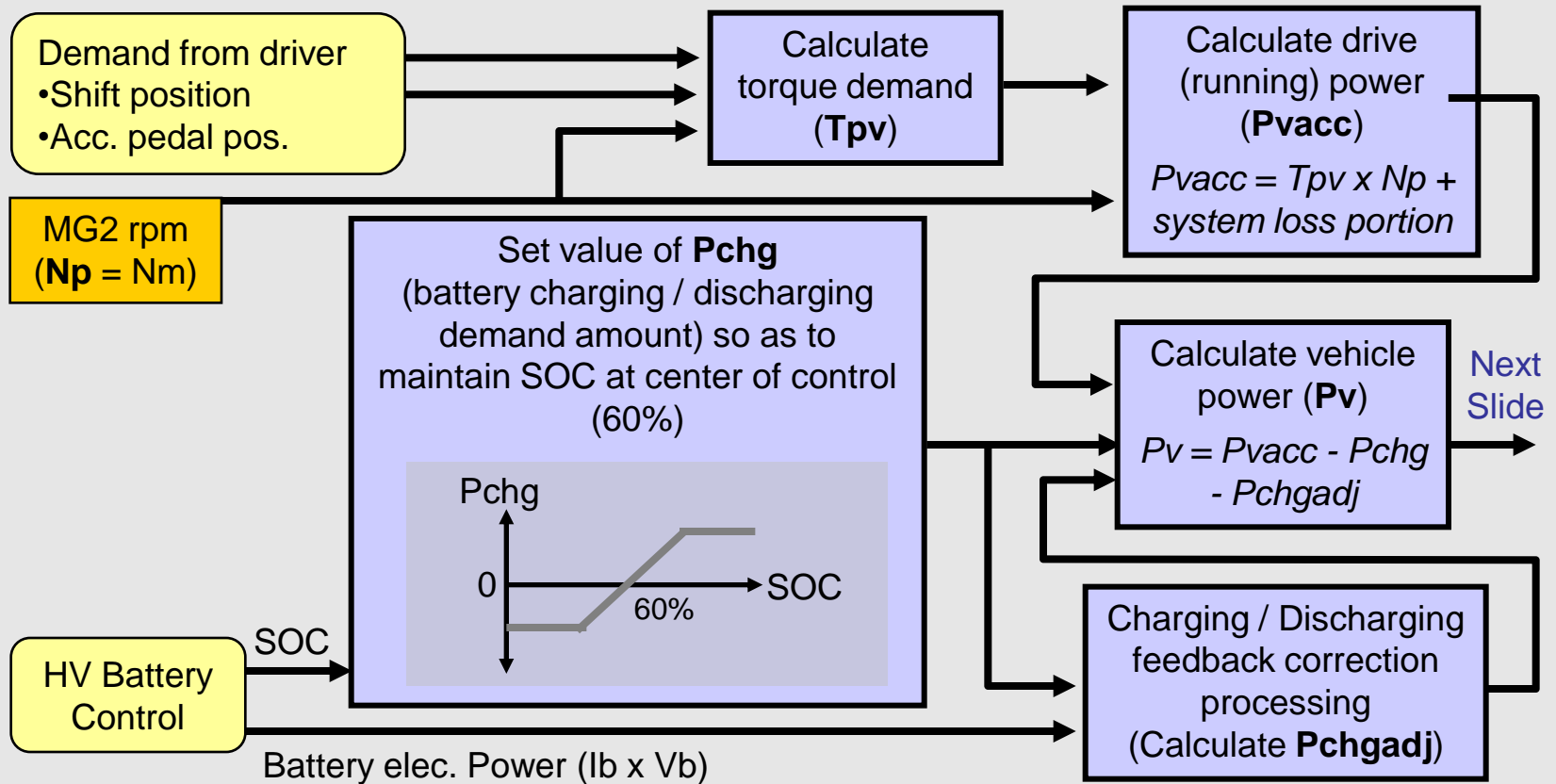


# HV & THS Control

Prius vs. RX400h

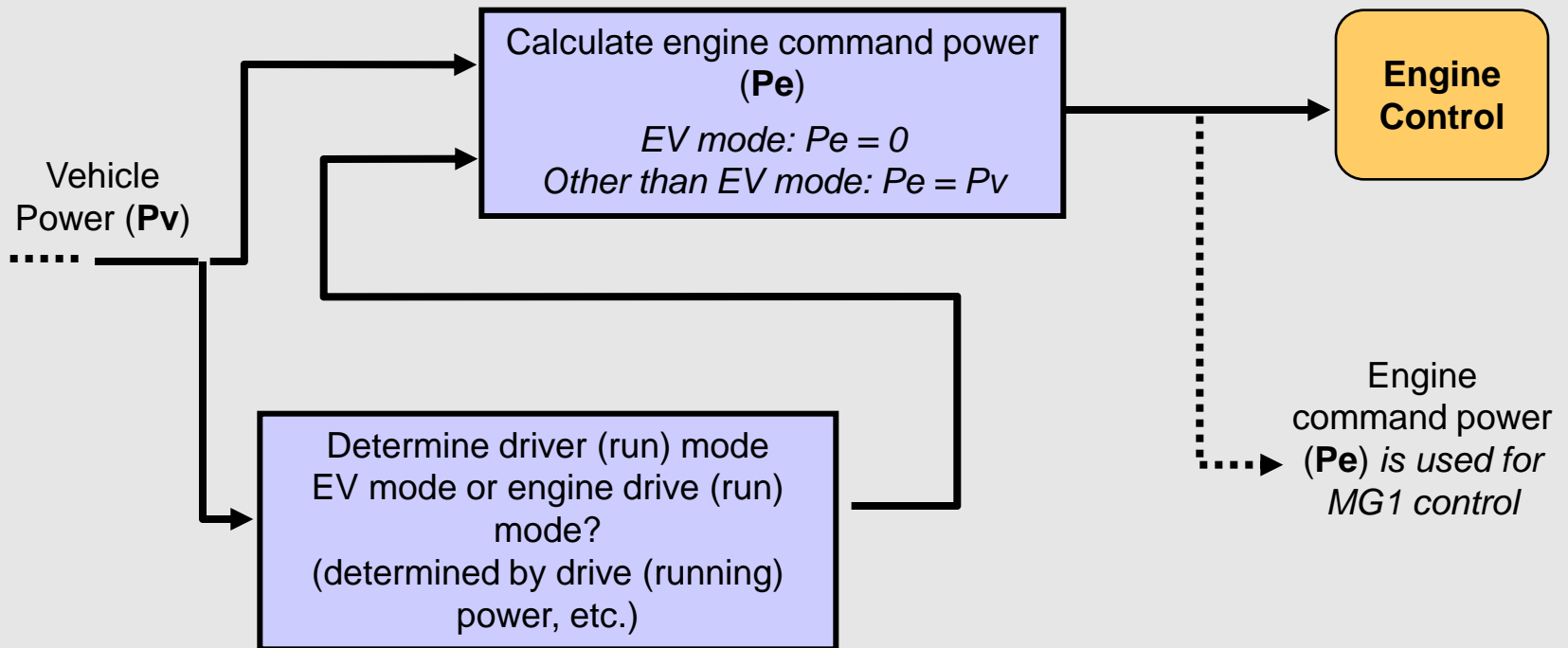
# Output Calculation

- Engine Control



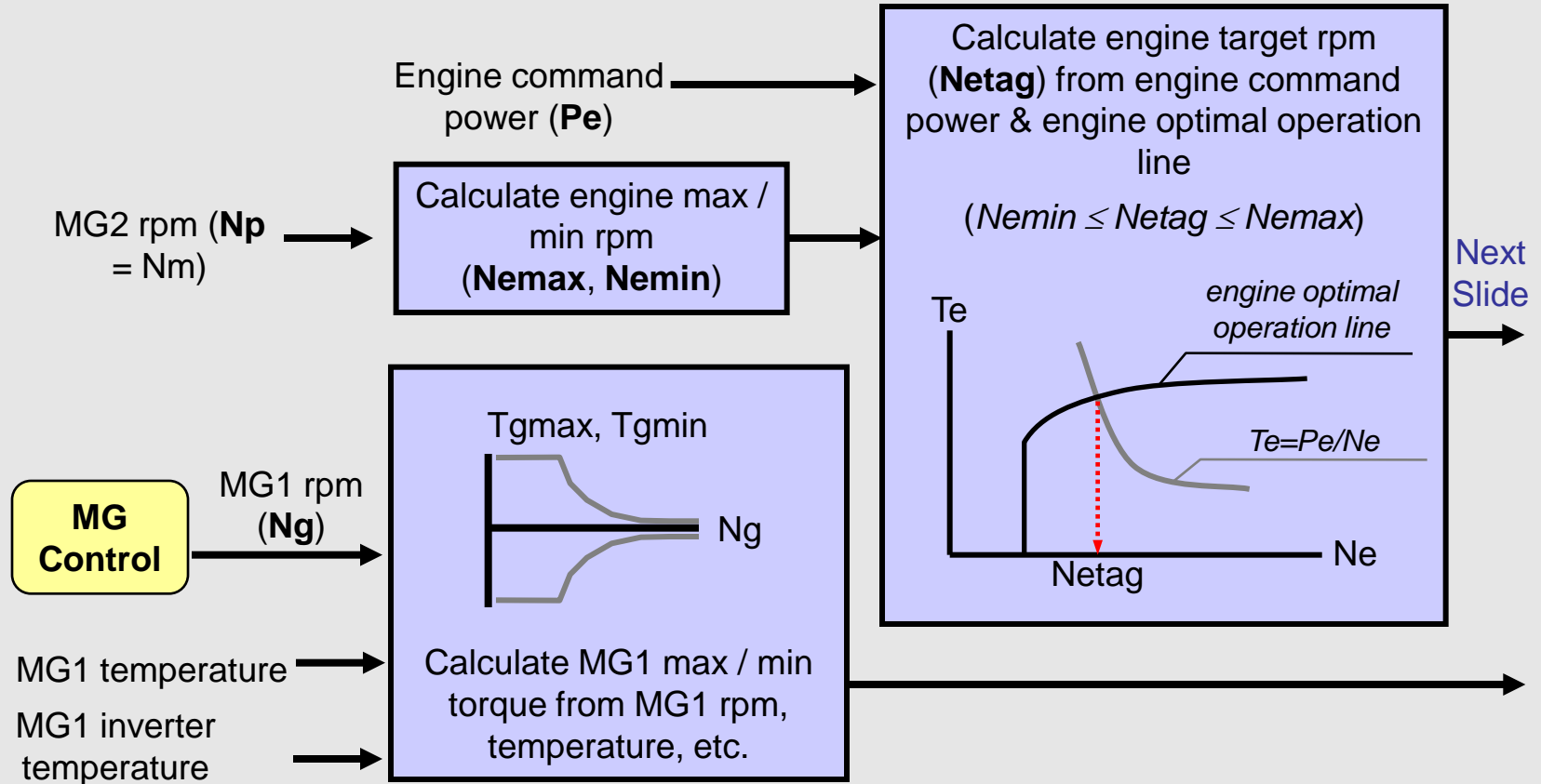
# Output Calculation

- Engine Control



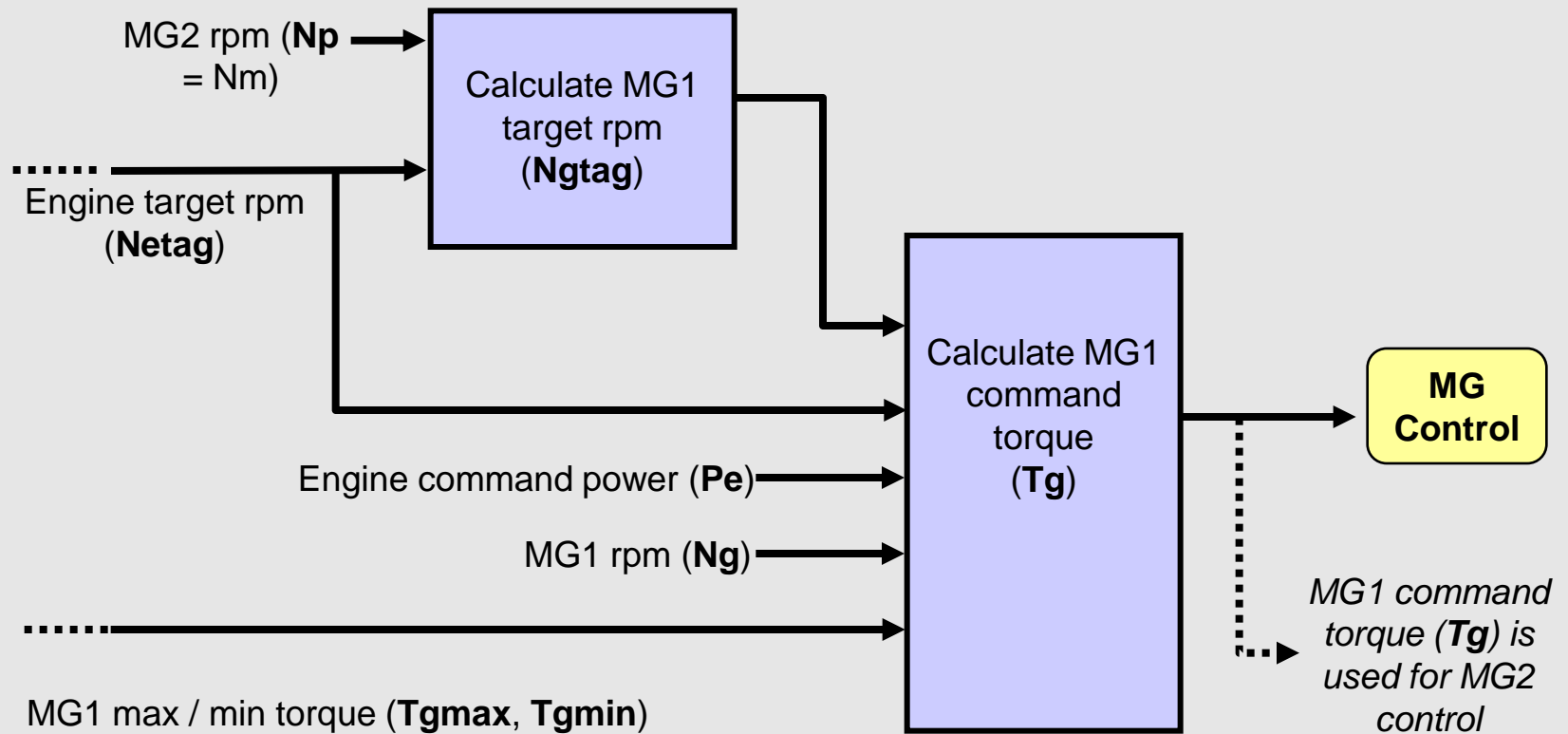
# Output Calculation

- MG1 Control



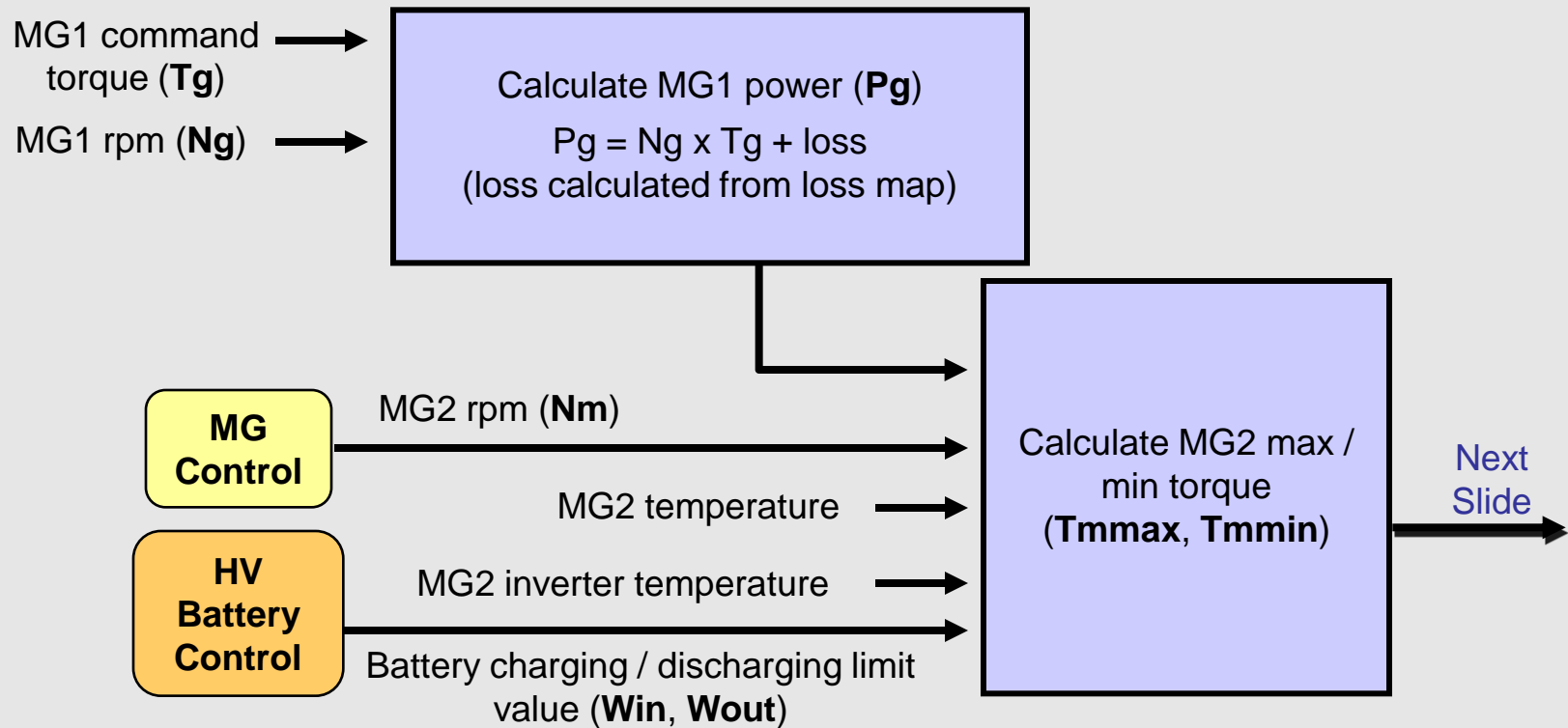
# Output Calculation

- MG1 Control



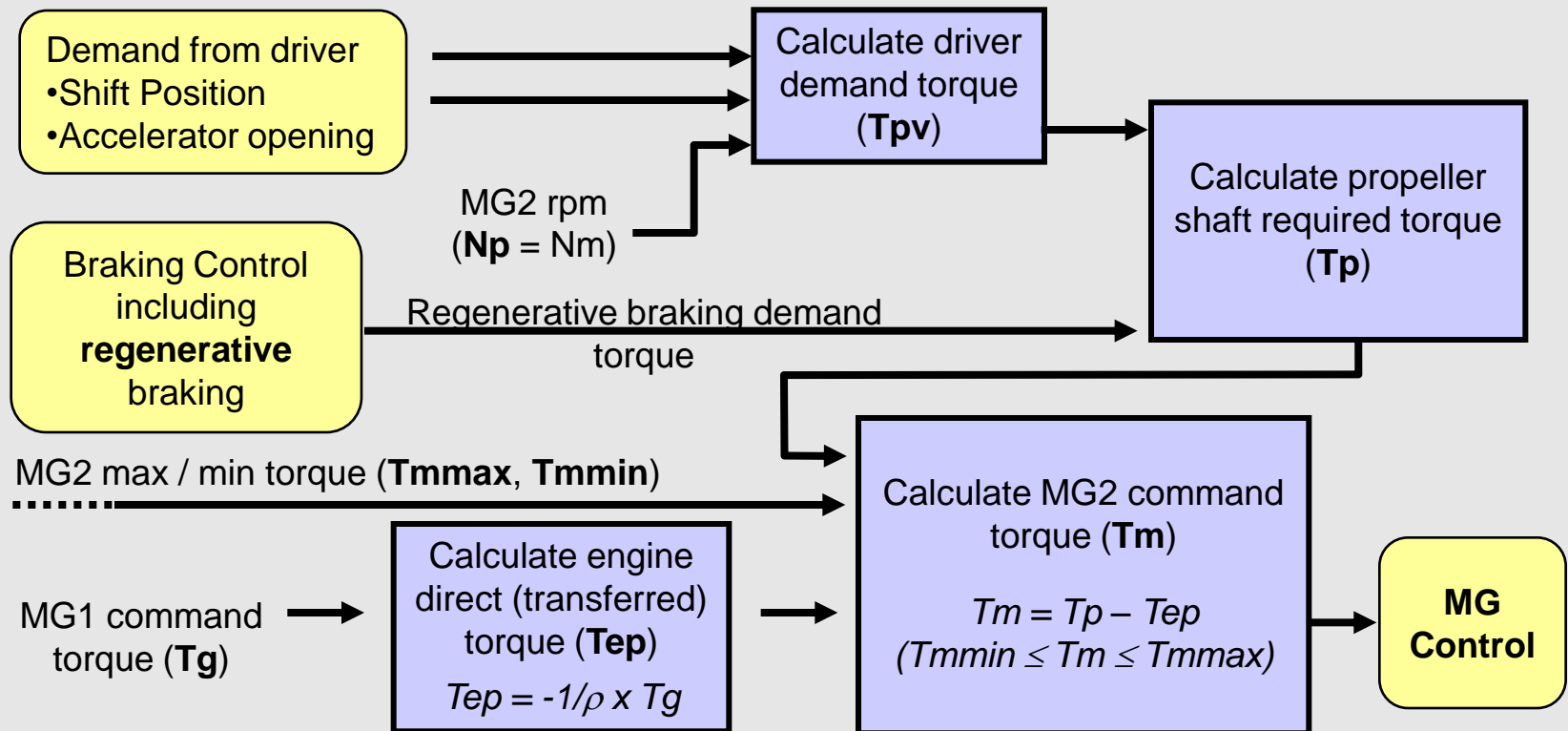
# Output Calculation

- MG2 Control



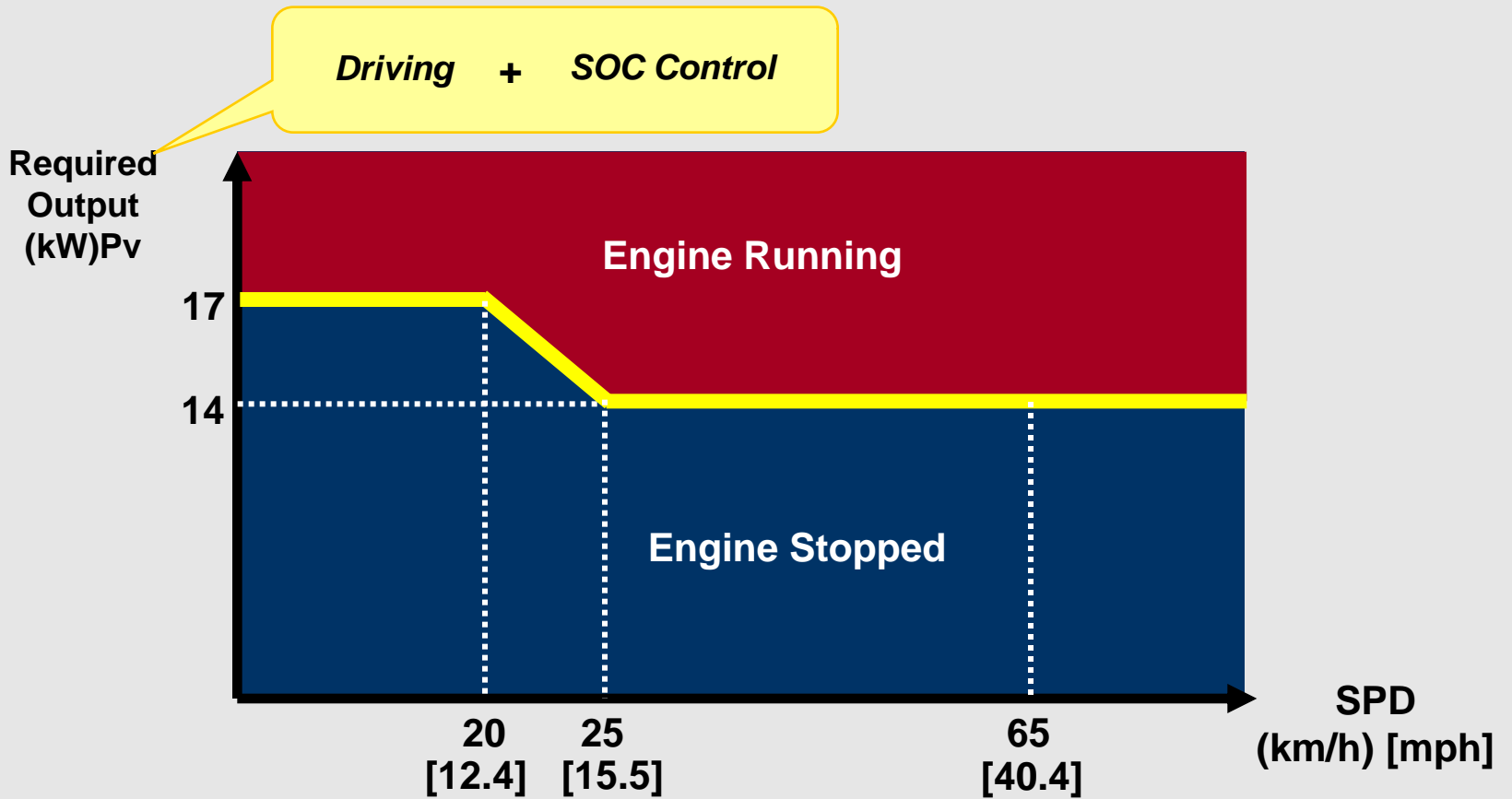
# Output Calculation

- MG2 Control



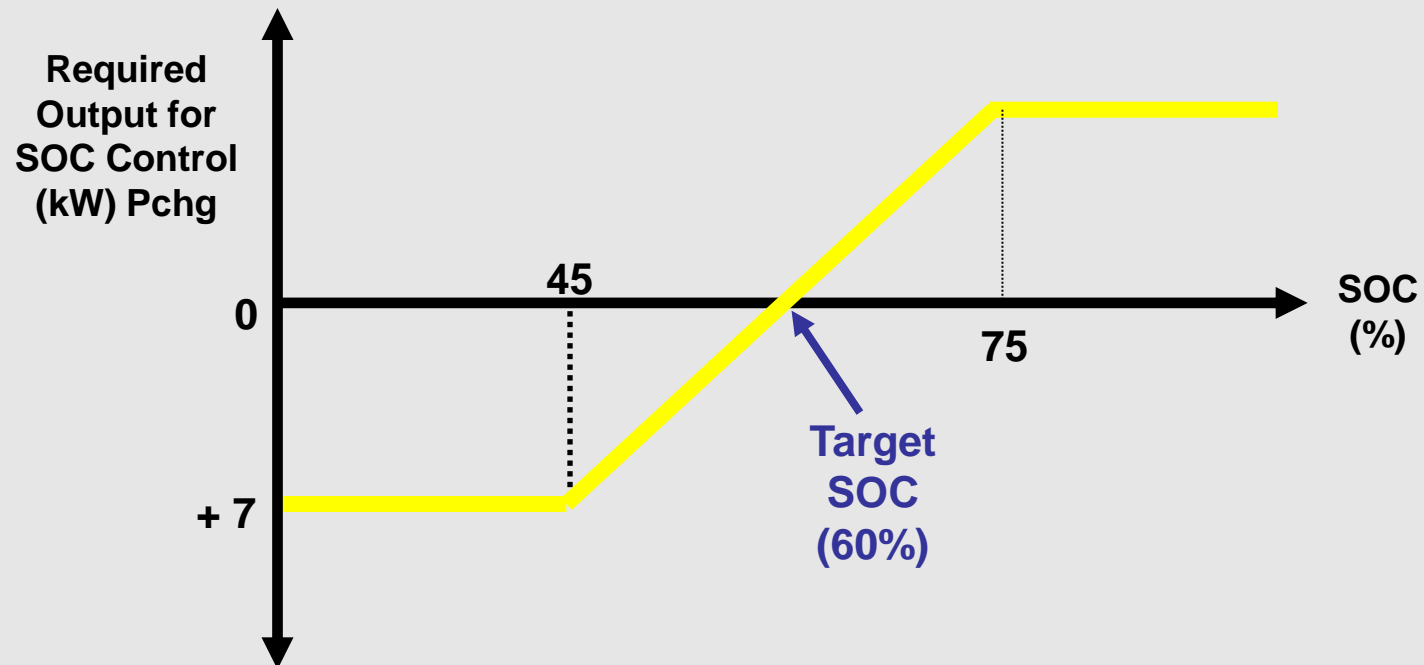
# Engine Start Condition

- At Driving



# Engine Start Condition

- Required output for SOC control

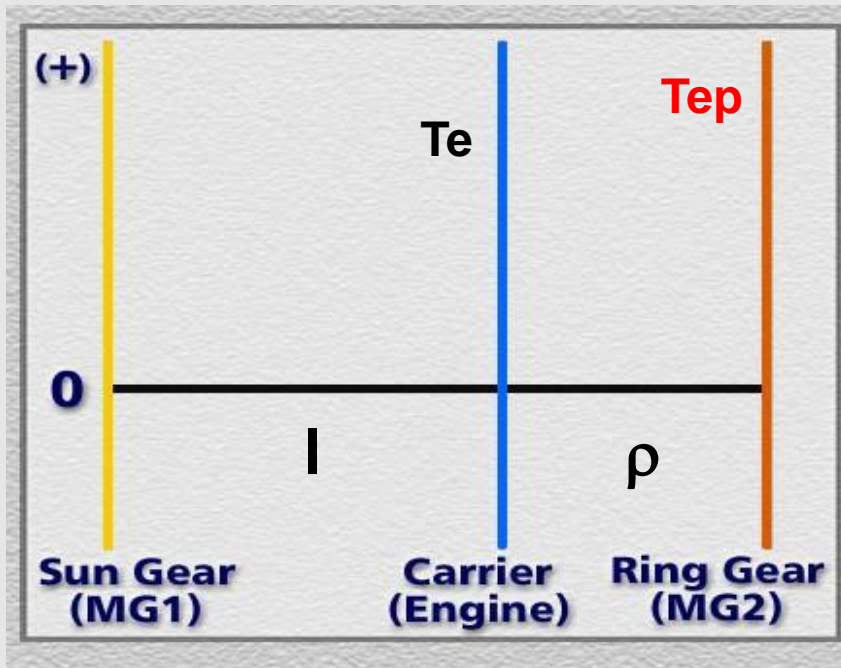


# Nomographic Chart

- General

- Engine torque is transferred to the ring gear (tire) as a driving force via the planetary gear unit

Engine Direct (Transferred) Torque ←



Engine Direct (Transferred)  
Torque

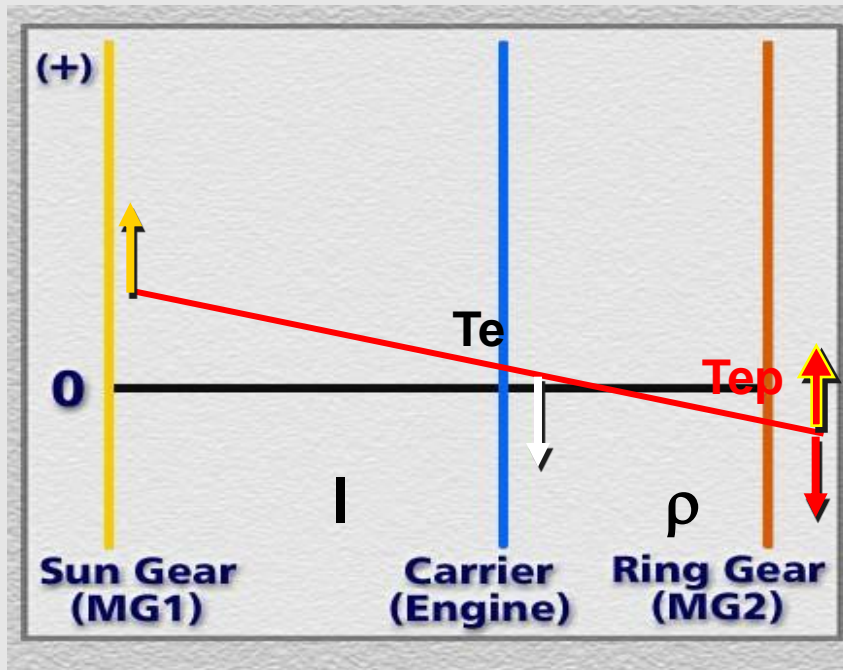
$$T_{ep} = l / (l + \rho) \cdot T_e$$

$$\rho = 0.3836$$

- Electric power generated by the MG1 is supplied to the MG2
- HV Battery makes up for energy shortage

# Nomographic Chart

- Reaction Force
  - When the engine starting, the MG1 drives the engine, and the reaction force transmitted to the ring gear (tire)



Cancel the reaction force

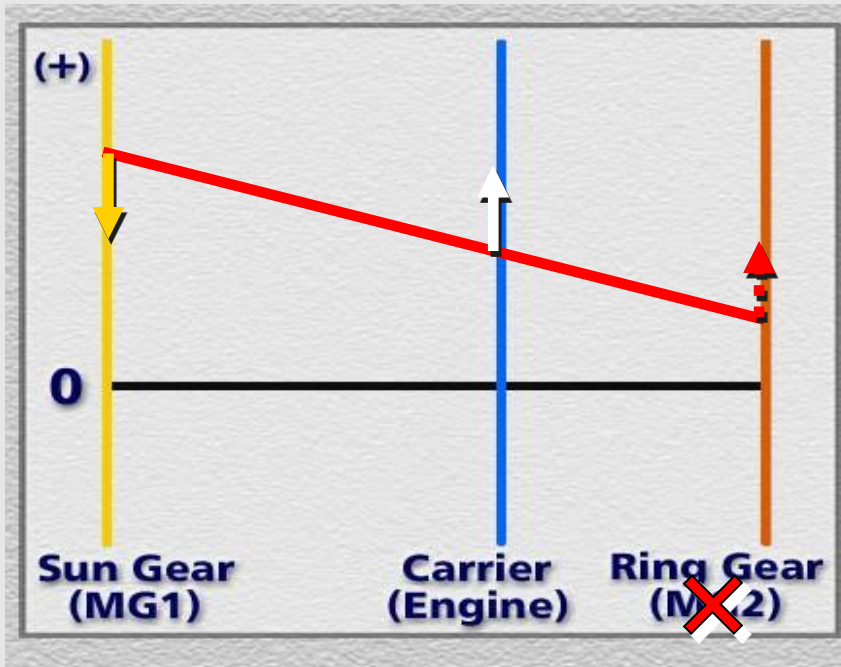


Shock is generated in the vehicle

The MG2 torque is generated to cancel the reaction force

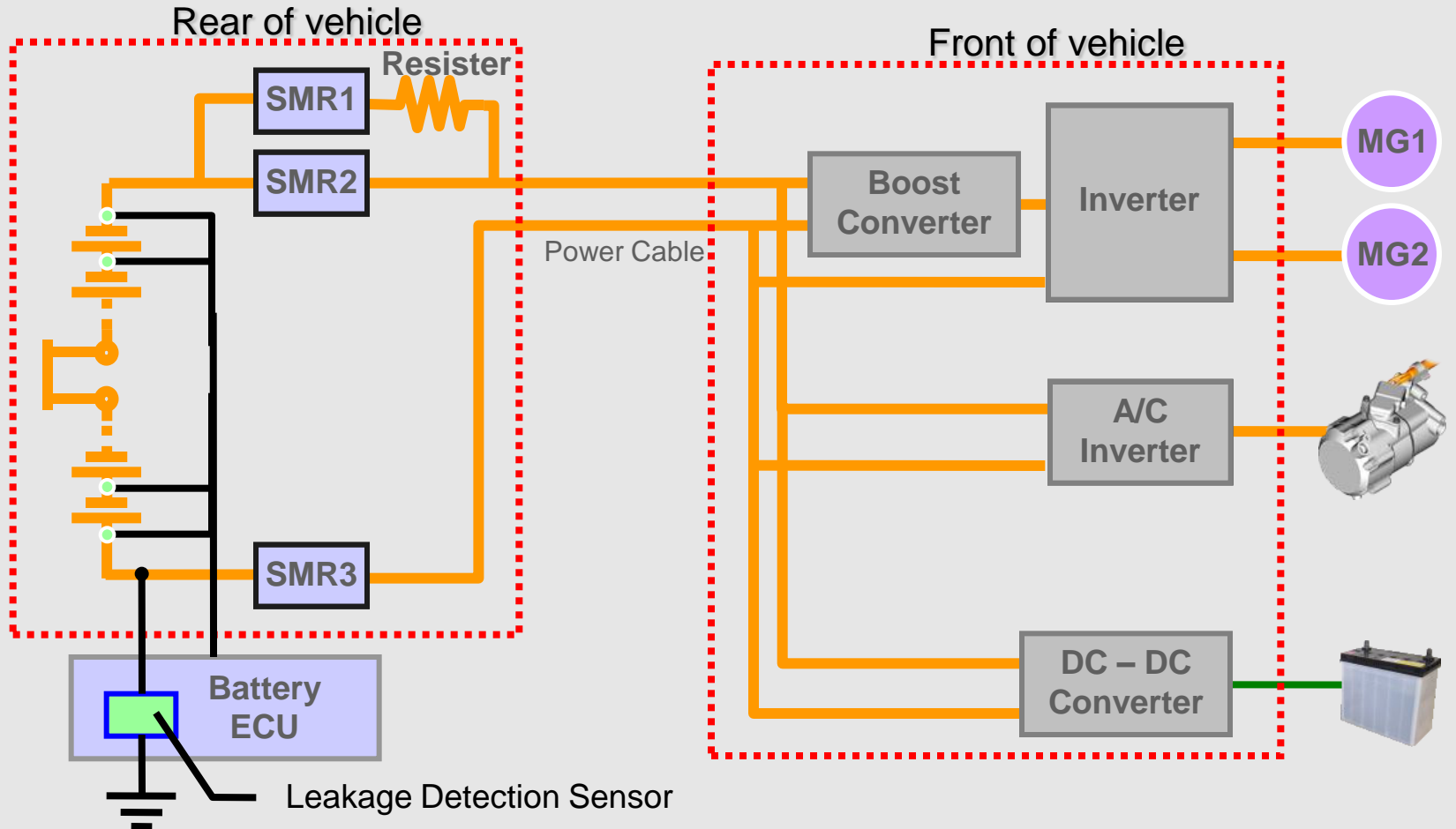
# Nomographic chart

- Example
  - MG2 malfunction



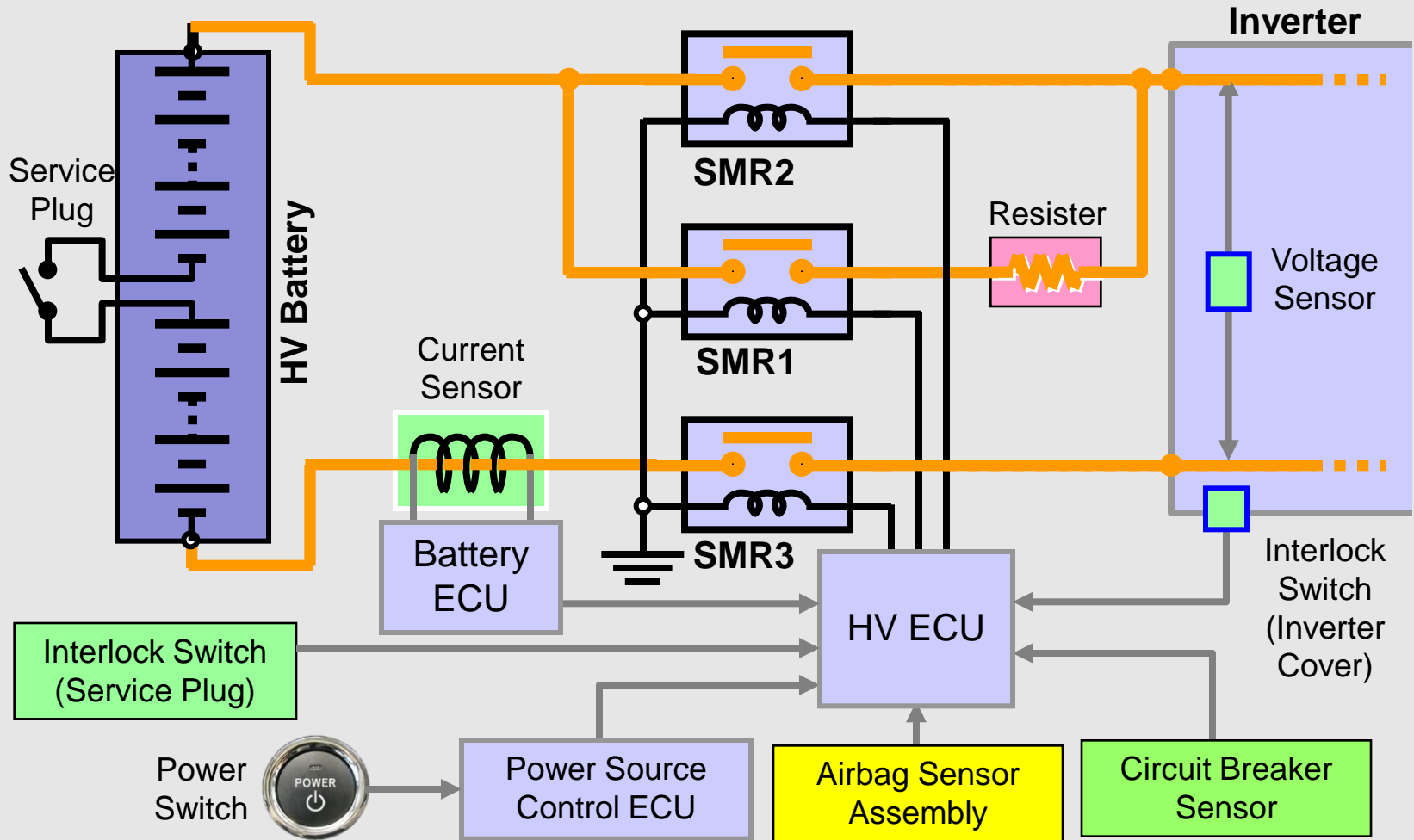
Driven by Engine and MG1

# System Main relay



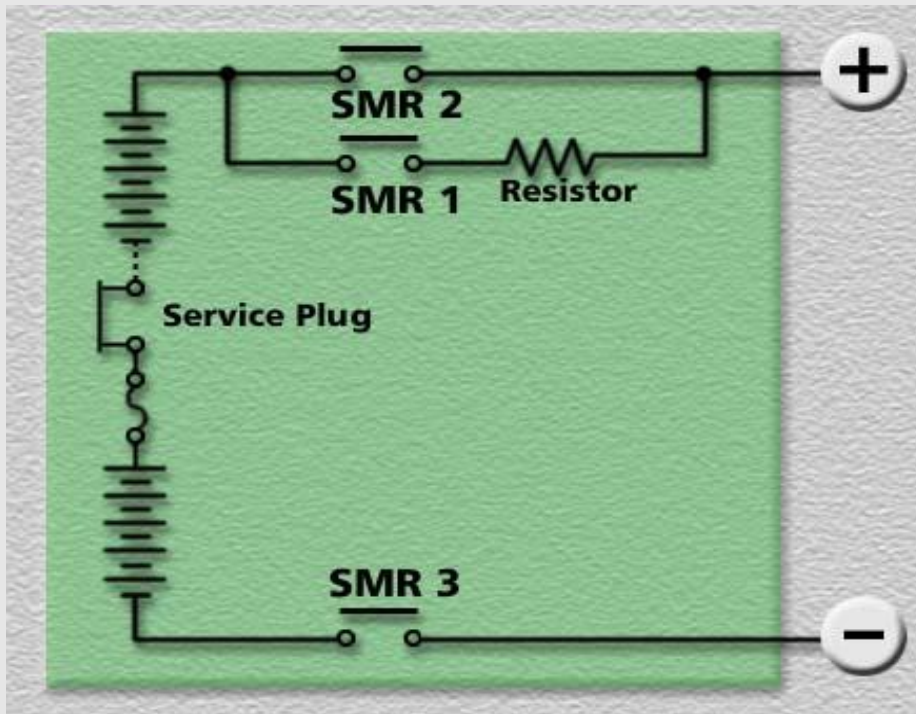
**Notice:** Detection area and malfunction portion is different

# SMR (System Main Relay)



# HV Battery

- SMR (System Main Relay)
  - READY ON



## STEP 1:

SMR 1 / SMR 3 → ON

## STEP 2:

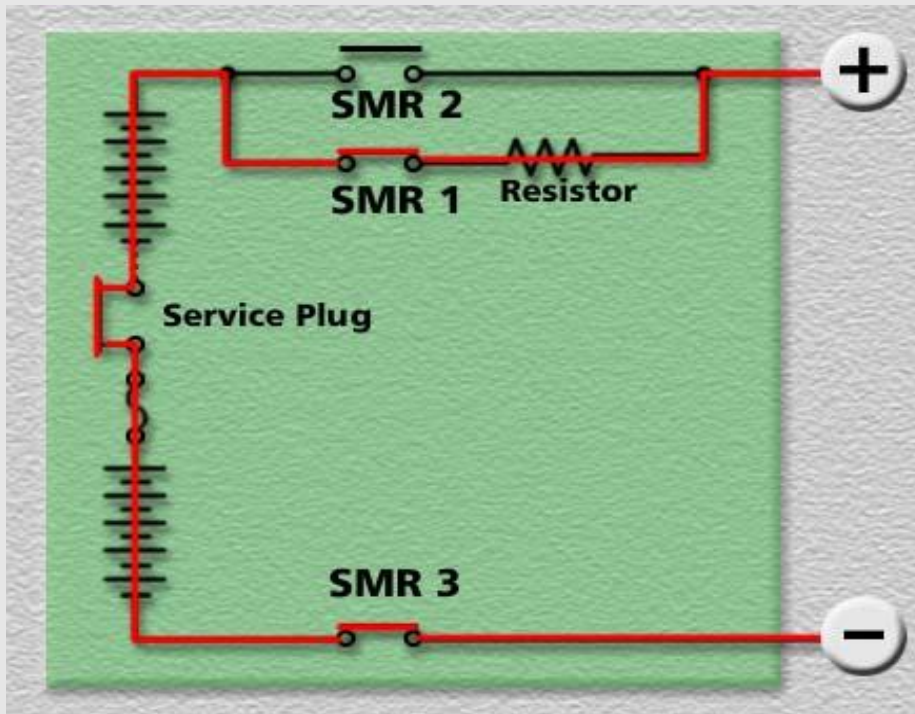
SMR 2 → ON

## STEP 3:

SMR 1 → OFF

# HV Battery

- SMR (System Main Relay)
  - READY ON



## STEP 1:

SMR 1 / SMR 3 → ON

## STEP 2:

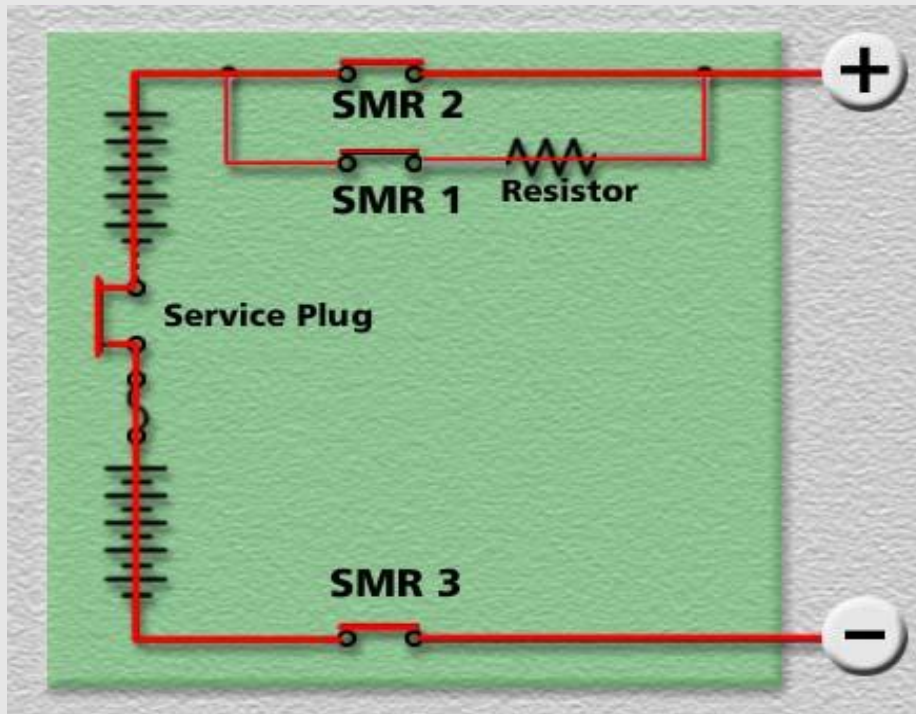
SMR 2 → ON

## STEP 3:

SMR 1 → OFF

# HV Battery

- SMR (System Main Relay)
  - READY ON



## STEP 1:

SMR 1 / SMR 3 → ON

## STEP 2:

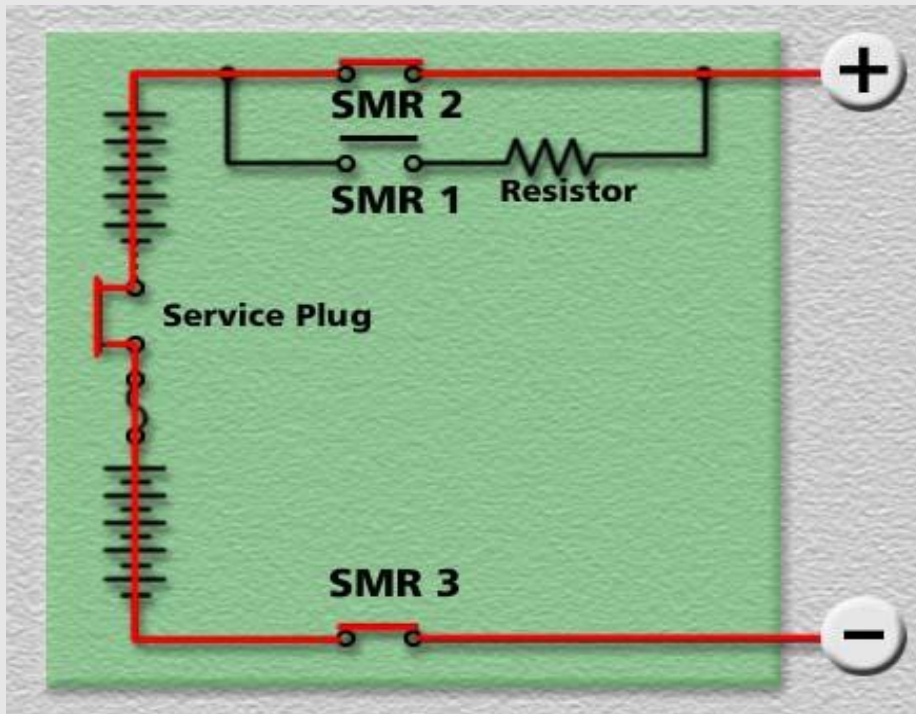
SMR 2 → ON

## STEP 3:

SMR 1 → OFF

# HV Battery

- SMR (System Main Relay)
  - READY ON



## STEP 1:

SMR 1 / SMR 3 → ON

## STEP 2:

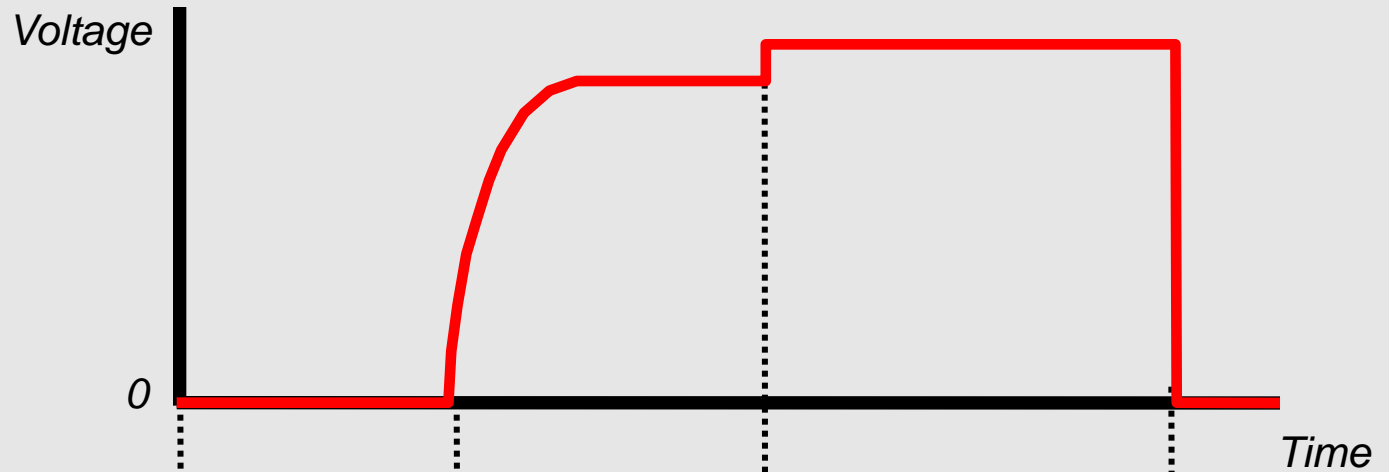
SMR 2 → ON

## STEP 3:

SMR 1 → OFF

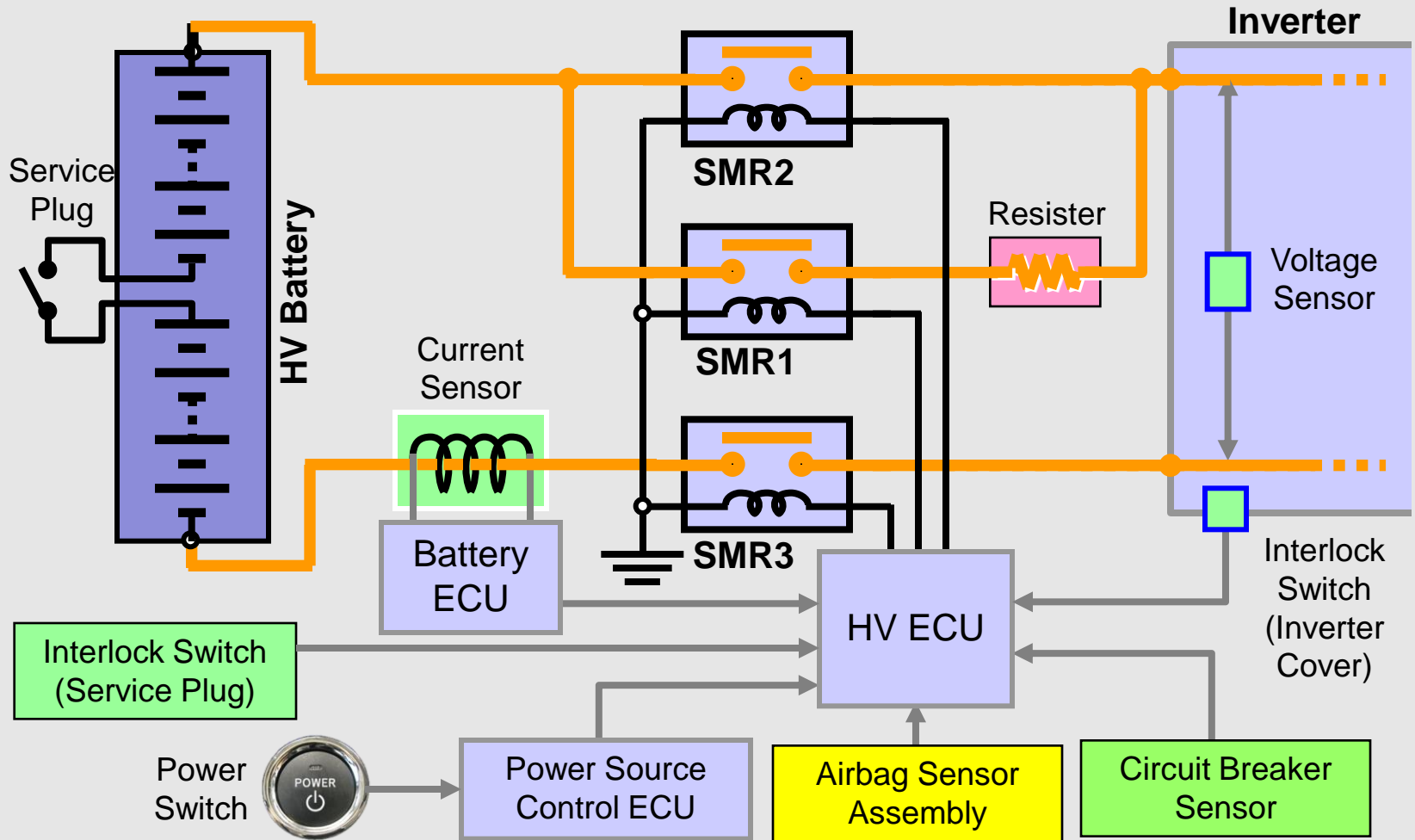
# SMR

- Operation and System Voltage



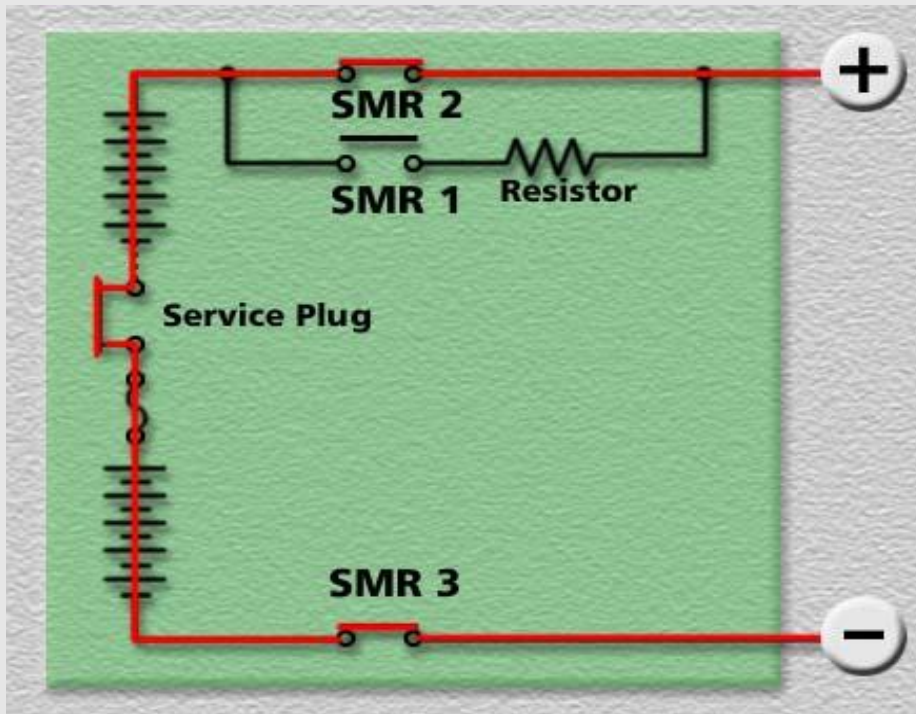
(+)	SMR1	OFF	ON	OFF	OFF
	SMR2	OFF	OFF	ON	OFF
(-)	SMR3	OFF	ON	ON	OFF

# SMR (System Main Relay)



# HV Battery

- SMR (System Main Relay)
  - Power OFF

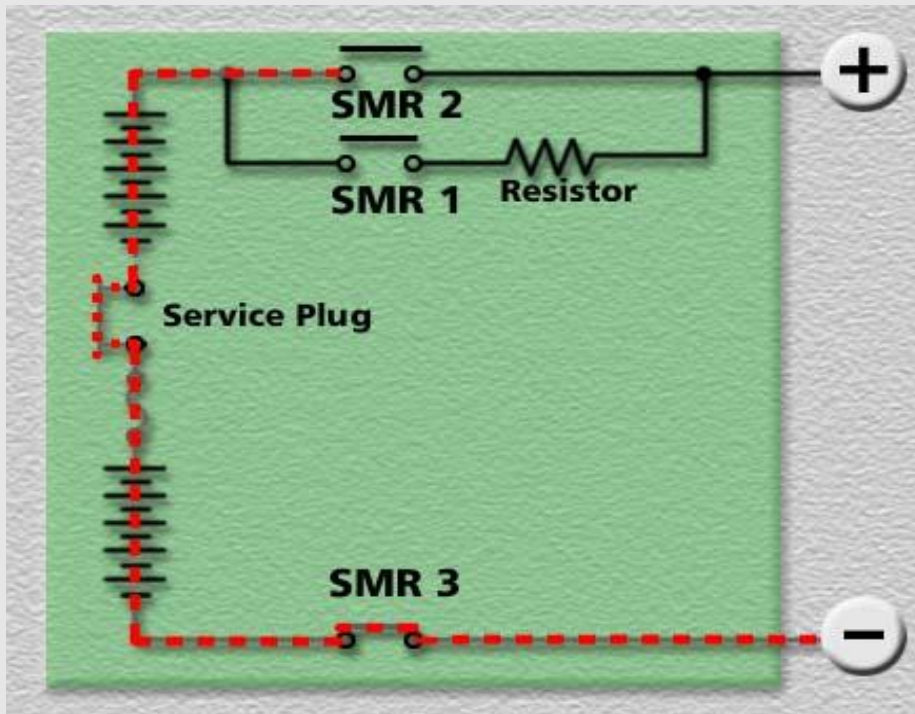


**STEP 1:**  
SMR 2 → OFF

**STEP 2:**  
SMR 3 → OFF

# HV Battery

- SMR (System Main Relay)
  - Power OFF

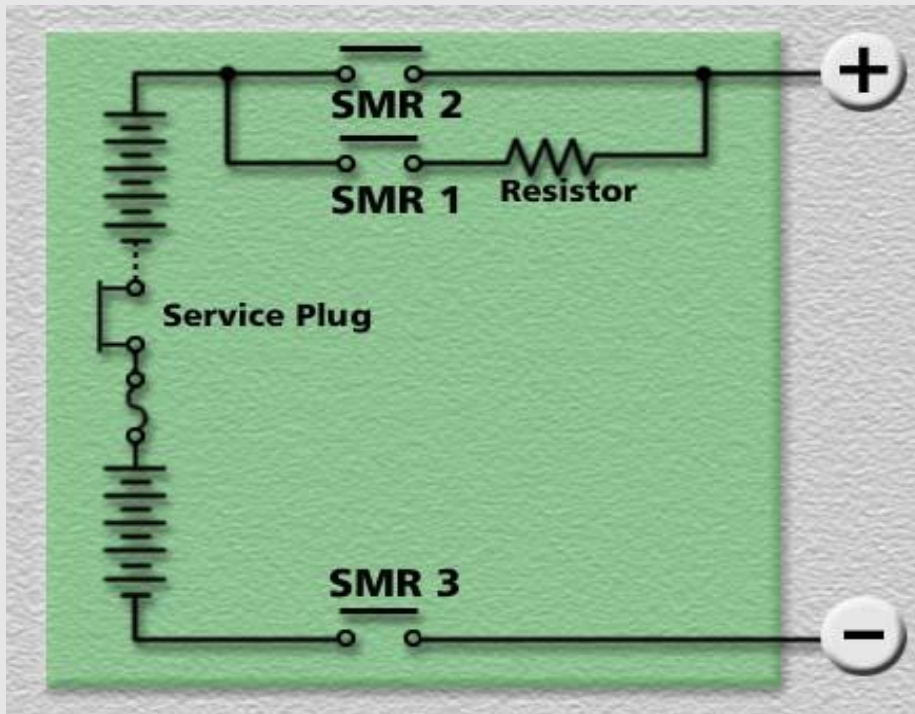


**STEP 1:**  
SMR 2 → OFF

**STEP 2:**  
SMR 3 → OFF

# HV Battery

- SMR (System Main Relay)
  - Power OFF



**STEP 1:**  
SMR 2 → OFF

**STEP 2:**  
SMR 3 → OFF

# SMR

- Diagnosis
  - Composition of SMR Diagnosis
  
- 1. HV ECU Internal Malfunction
  
- 2. Sensor or Actuator Malfunction
  - SMR Coil Open
  - Open or Short in Voltage Sensor Circuit
  - SMR Close Stuck
  
- 3. System Logical Deviation
  - High-voltage Wire Harness Malfunction

# SMR

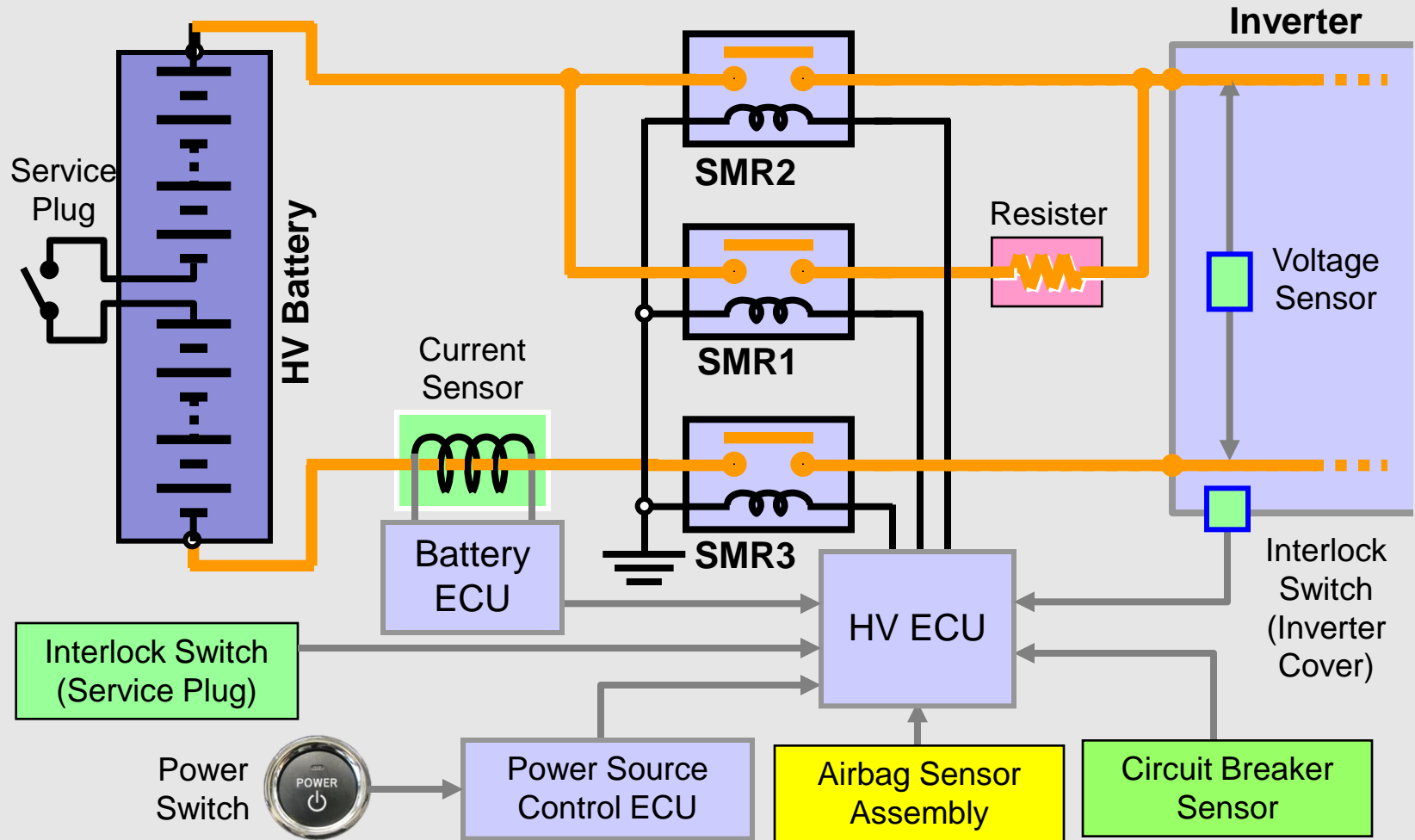
- Diagnosis
  - Sensor or Actuator Malfunction
    - › SMR Close Stuck

No.	Detection Item	Detection Method
1	SMR2	SMR2 OFF → SMR3 OFF
2	SMR3	SMR1 ON
3	SMR2 and SMR3	Discharging
4	SMR1	SMR3 ON

Immediately after the IG/ON

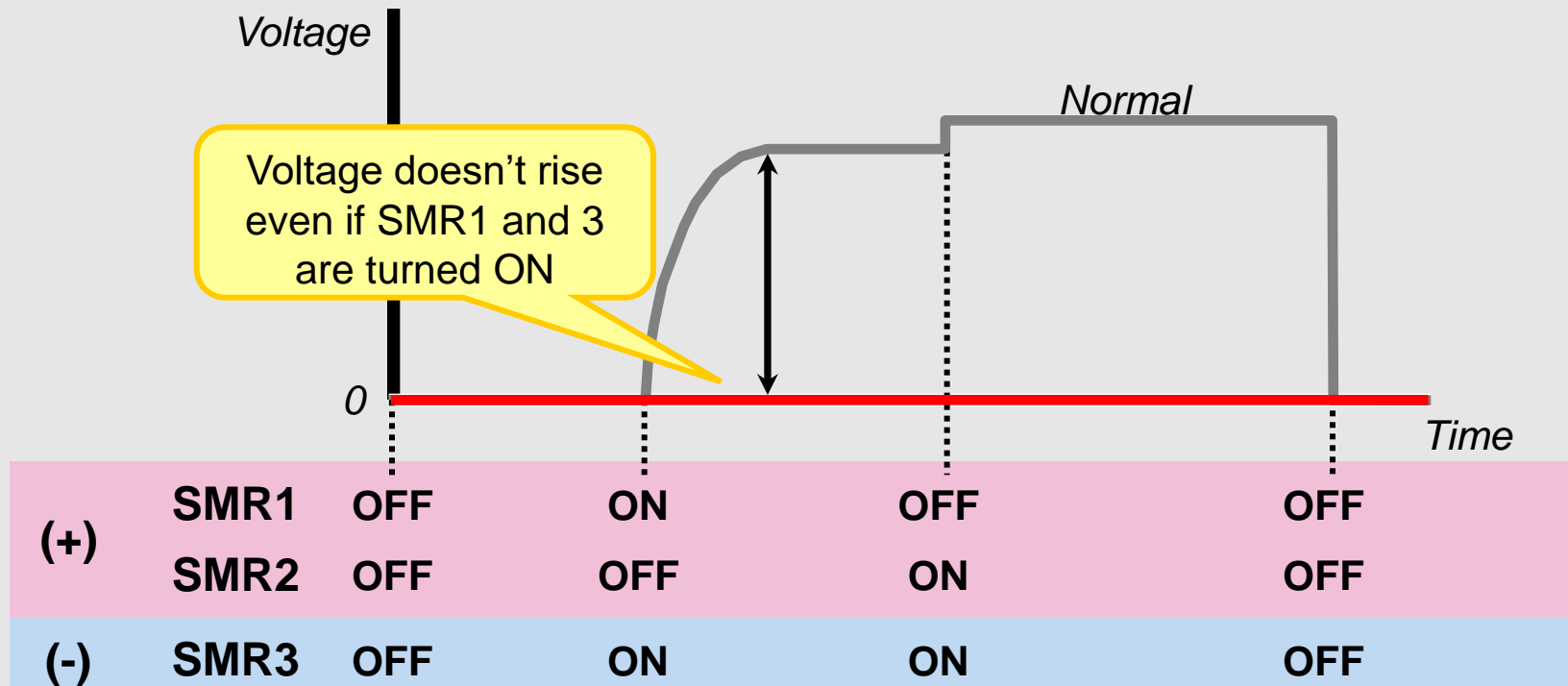
only for RX400h

# SMR (System Main Relay)



# SMR

- Diagnosis
  - System Logical Deviation
    - › High-voltage Wire Harness Malfunction



# Motor Control

- Diagnosis

- Motor Control

1. HV ECU Internal Malfunction

2. Sensor or Actuator Malfunction

- Resolver
- Current Sensor
- Temperature Sensor etc.

} Open / Short Circuit,  
Range/Performance  
Problem

3. System Logical Deviation

- Over-voltage, Over-current, Overheat
- Gate Logical Deviation, MG1/2 System Malfunction, Motor Inverter Gate Malfunction, Monitoring MG1/2 Torque Performance, Magnetic Force Deterioration

# Motor Control

- Diagnosis
  - 3. System Logical Deviation
- Over-voltage, Over-current, Overheat
  - Monitors the sensor signal  
(When DTC is detected, HV system is shutdown  
→ it cannot drive)
- Gate Logical Deviation
  - The IGBT operation by the U.V.W signal is not correct
- MG1/2 System Malfunction
  - Actual current is different from the target current

**Target Current: Calculated by the motor drive command  
(Transistor ON/OFF)**

# Motor Control

- Diagnosis
  - 3. System Logical Deviation
- Motor Inverter Gate Malfunction  
(MG1: P0A7A-522 / MG2: P0A78-510)
  - There is still current after transmitting the shut down signal
- Monitoring MG1/2 Torque Performance  
(MG1: P0A7A-344 / MG2: P0A78-306)
  - Actual torque is different from the target torque

**Actual Torque: Calculated from the current and speed/position of the motor**

**Target Torque: Calculated by the motor drive command (Transistor ON/OFF)**

# Motor Control

- Diagnosis
  - 3. System Logical Deviation

## Magnetic Force Deterioration

(MG1: P0A92-261)

(MG2: P0A90-251)

### Features of Magnet

- It is weak against heat
- When magnetism decreases once, it doesn't revive by it self

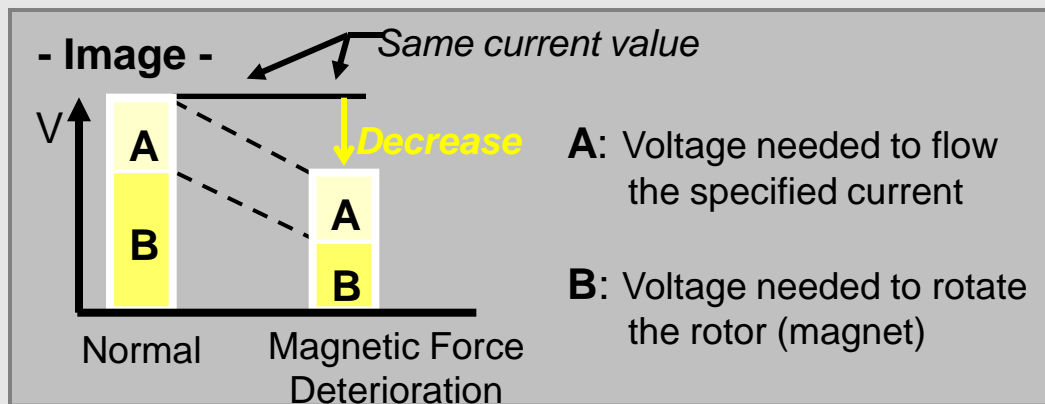
# Motor Control

- Diagnosis
  - 3. System Logical Deviation

## Detection of Magnetic Force Deterioration

1. To become a specified current value, the motor drive voltage is controlled
2. The voltage is monitored

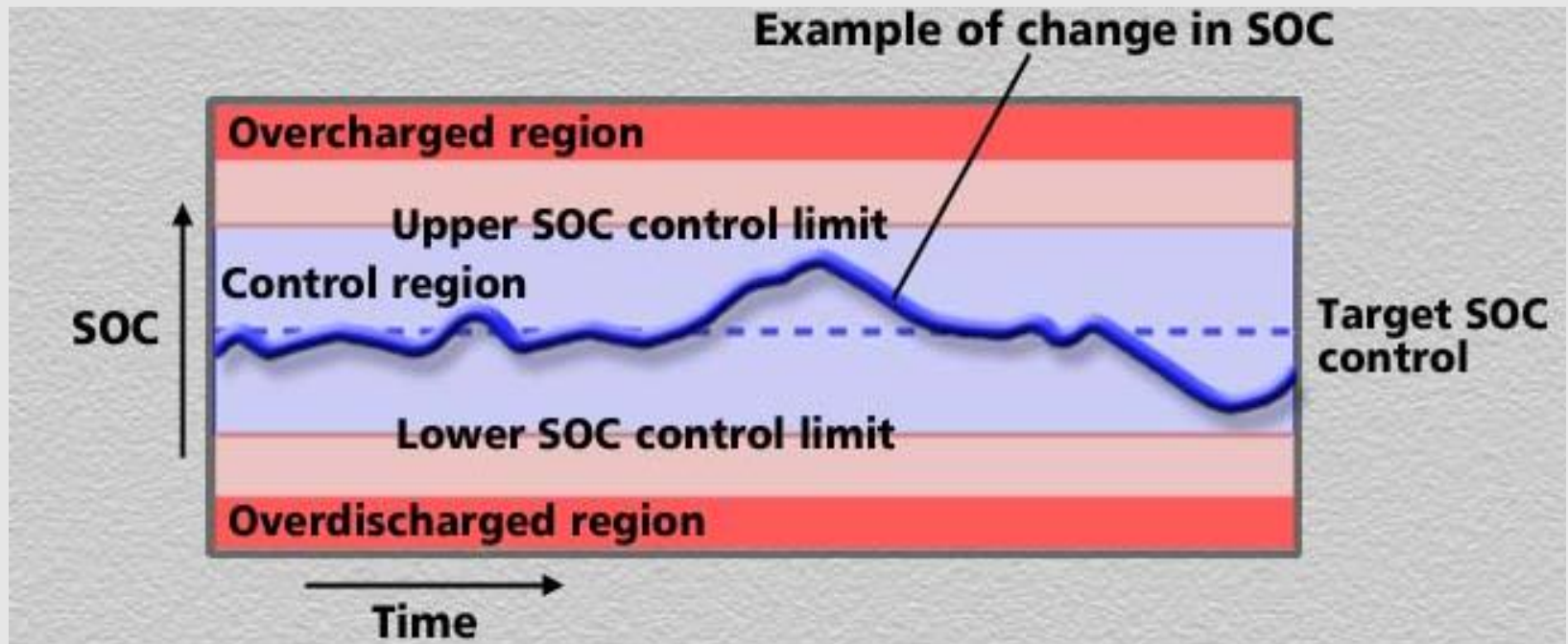
Voltage decreases when magnetic force deterioration  $U=B \times I \times v$



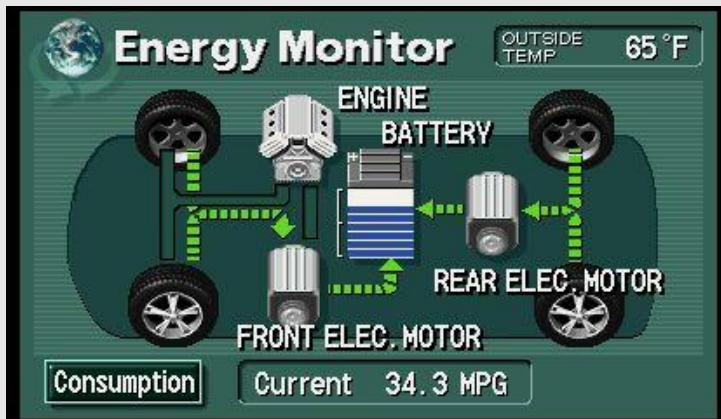
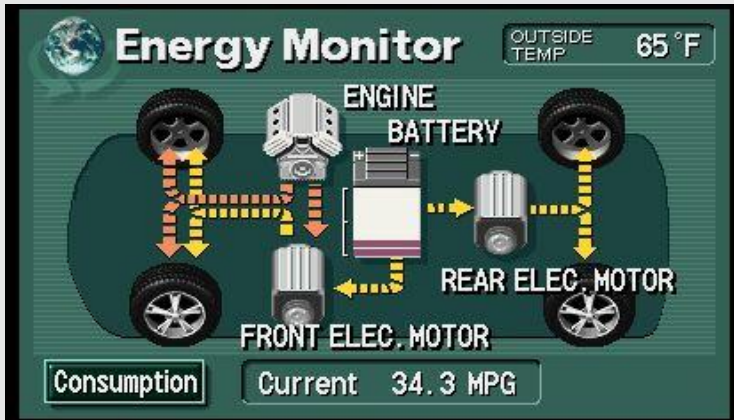
# HV Battery

- What is the SOC ?

SOC (State of Charge) = Charging Rate



# HV Battery



## SOC Indication

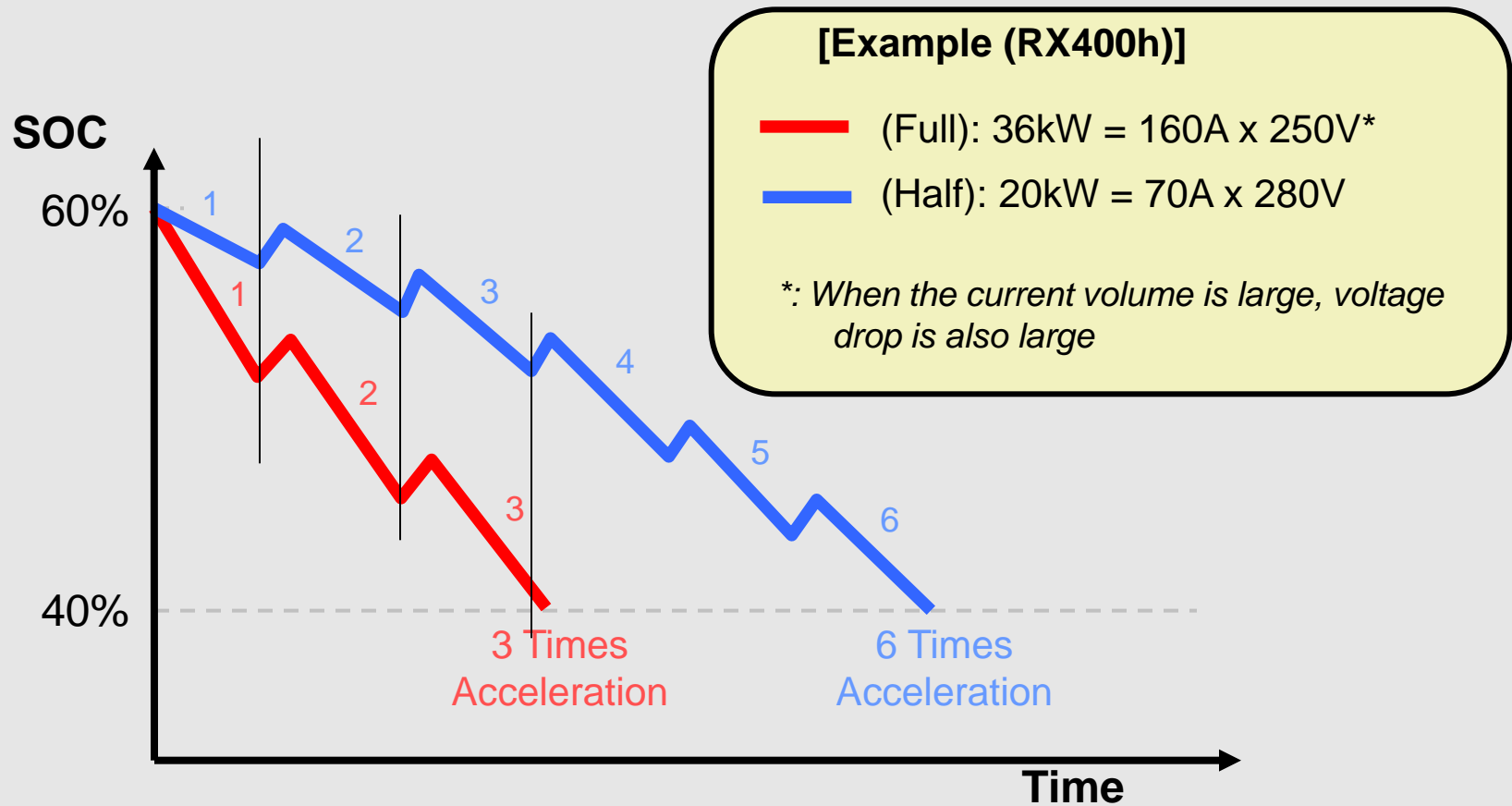
- SOC is indicated in 8 segments

Color	Number of Segment
Green	7 ~ 8
Blue	3 ~ 6
Purple	1 ~ 2

- 8-segment  $\neq$  SOC 100%
- 0-segment  $\neq$  SOC 0%
- Power is determined by temperature (not by SOC)

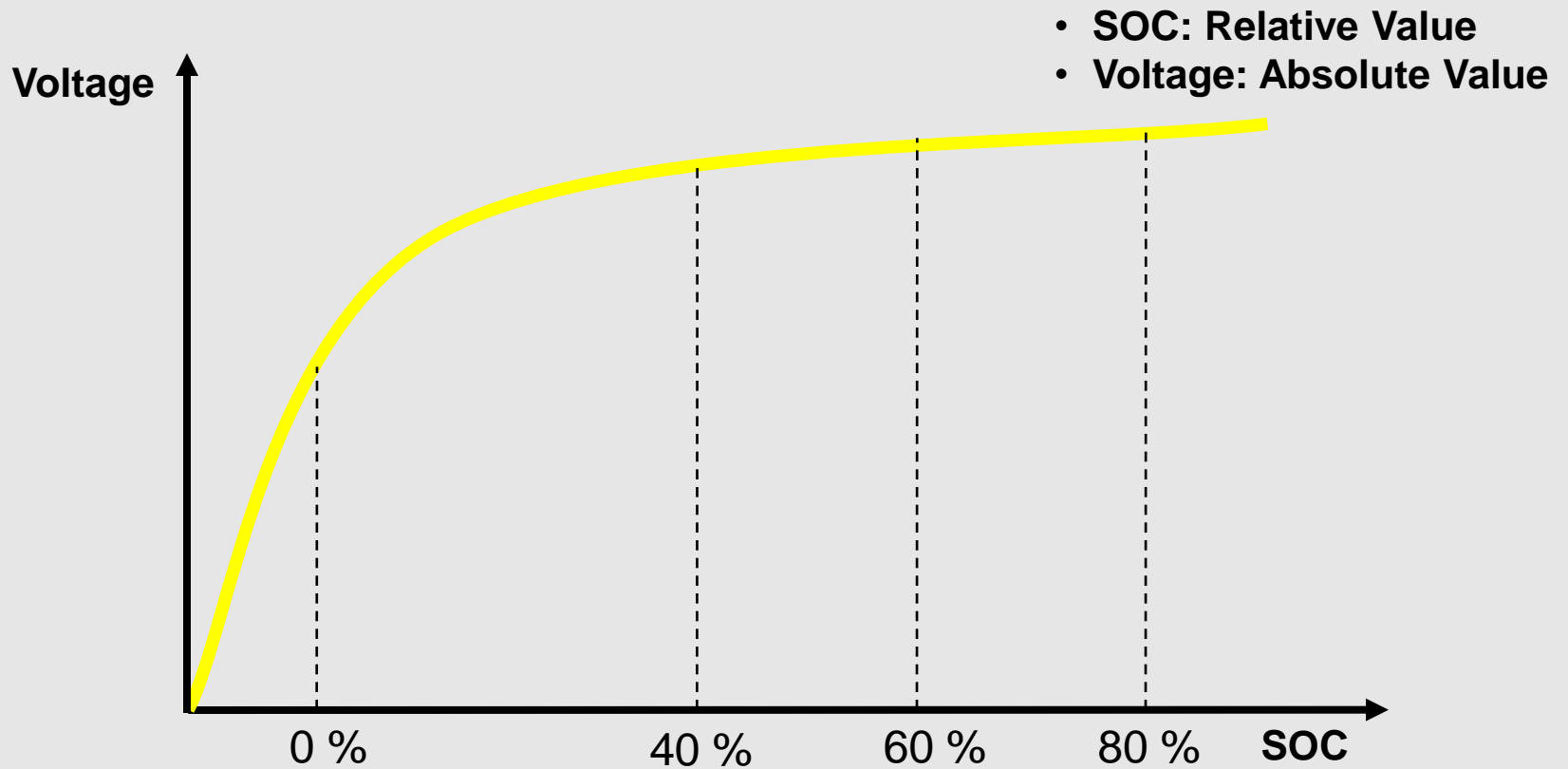
# HV Battery

- SOC Calculation
  - SOC is calculated by current volume (IN / OUT)



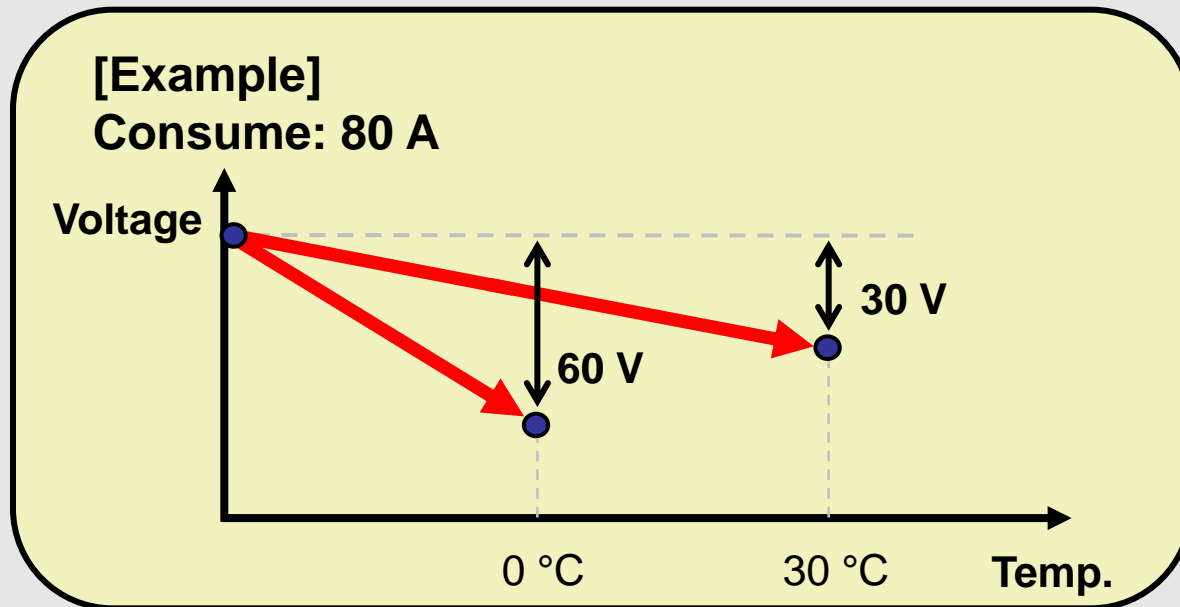
# HV Battery

- SOC Calculation
  - SOC and Voltage



# HV Battery

- SOC Calculation
  - Voltage and Temperature

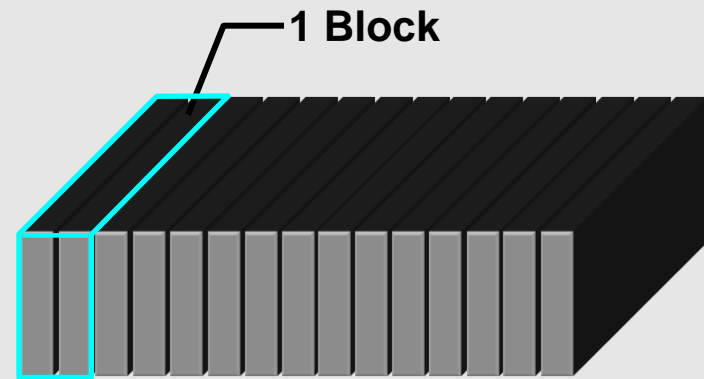
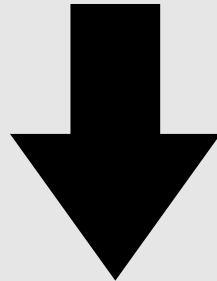


The voltage drop is different depending on the temperature, even if the SOC decrease is same

# HV Battery

- SOC Calculation

Monitors the SOC of each  
block



**P0A7F:** Battery pack deterioration

**P0A80:** Voltage difference

**P3011 – P3025:** Malfunction of each block

# HV Battery

- Diagnosis / Fail-safe (1) (RX400h)

	DTC No.		Vehicle Condition		Failsafe	
Battery ECU	P0A1F		All Battery Monitoring becomes impossible		[Drive by engine] or [READY OFF]	
			Some Battery Monitoring becomes impossible		Limit the battery input/output	
Voltage Sensor	P3030		Voltage monitoring impossible	Control level of some controls (SOC calculation, diagnosis) deteriorates		
Current Sensor	P0ABF		Current monitoring impossible			Limit the battery input/output
	P0AC0					
P0AC1						
P0AC2						
Temperature Sensor	P0A9C	P0AC8	Temperature monitoring impossible	Control level of some controls (SOC calculation, diagnosis) deteriorates	Limit the battery input/output	
	P0A9D	P0ACA				
	P0A9E	P0ACC				
	P0AC5	P0ACD				
	P0AC7					

# HV Battery

- Diagnosis / Fail-safe (2) (RX400h)

	DTC No.		Vehicle Condition	Failsafe
Cooling System	P0A82	P0A9A P0AD0 P0AD2 P0AD3	By the inability of cooling performance, battery temperature rises	Limit the battery output
	P0A84 P0A85 P0A97 P0A99			
Battery	P0A7F		By the deterioration of battery performance, SOC decrease at discharge becomes fast	-
	P0A80		Battery cell malfunction	Limit the battery input/output
	P3011 – P3025		Battery cell malfunction	[Limit the battery input/output] or [Drive by engine] or [READY OFF]
Communication	P3015		Battery monitoring inability	[Drive by engine] or [READY OFF]

# HV Battery

- Diagnosis / Fail-safe (3) (RX400h)

	DTC No.	Vehicle Condition	Failsafe
System	P0A95	High-voltage fuse blows	[Drive by engine] or [READY OFF]
	P0AF8	Voltage drop caused by malfunction in other system	READY OFF
	P3000-603	Temperature rises caused by malfunction in other system	[Drive by engine] or [READY OFF]
	P3000-388	SOC becomes very low (By the malfunction in other system, Vehicle is left in N range, Continues driving out of gas)	
	P3000-389	Voltage drops caused by malfunction in other system	READY OFF
	P3000-390	SOC becomes very high caused by the malfunction in other system	EV driving (Engine stop)
	P3004-133	Discharge current becomes over-current caused by malfunction in other system	READY OFF

# HV Battery

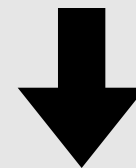
- Output Limit

## Output Limit Conditions

1. High / Low Temperature
2. SOC is lower limit
3. Voltage is lower limit
4. Malfunction is detected



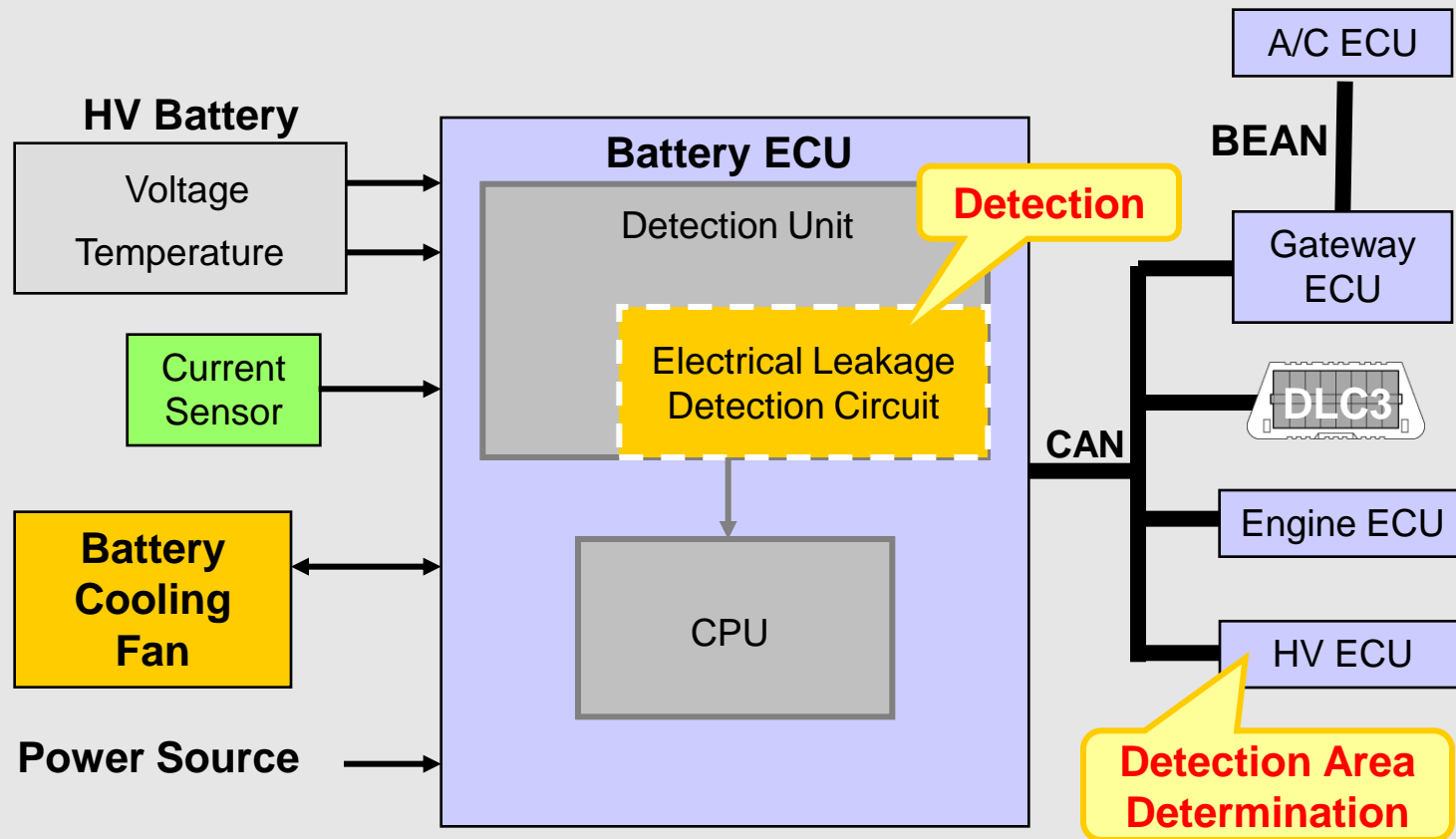
The output decrease of HV battery  
is covered by the engine output  
increase



**There is almost no influence  
to the drivability**

# Leakage Detection High Voltage Circuit

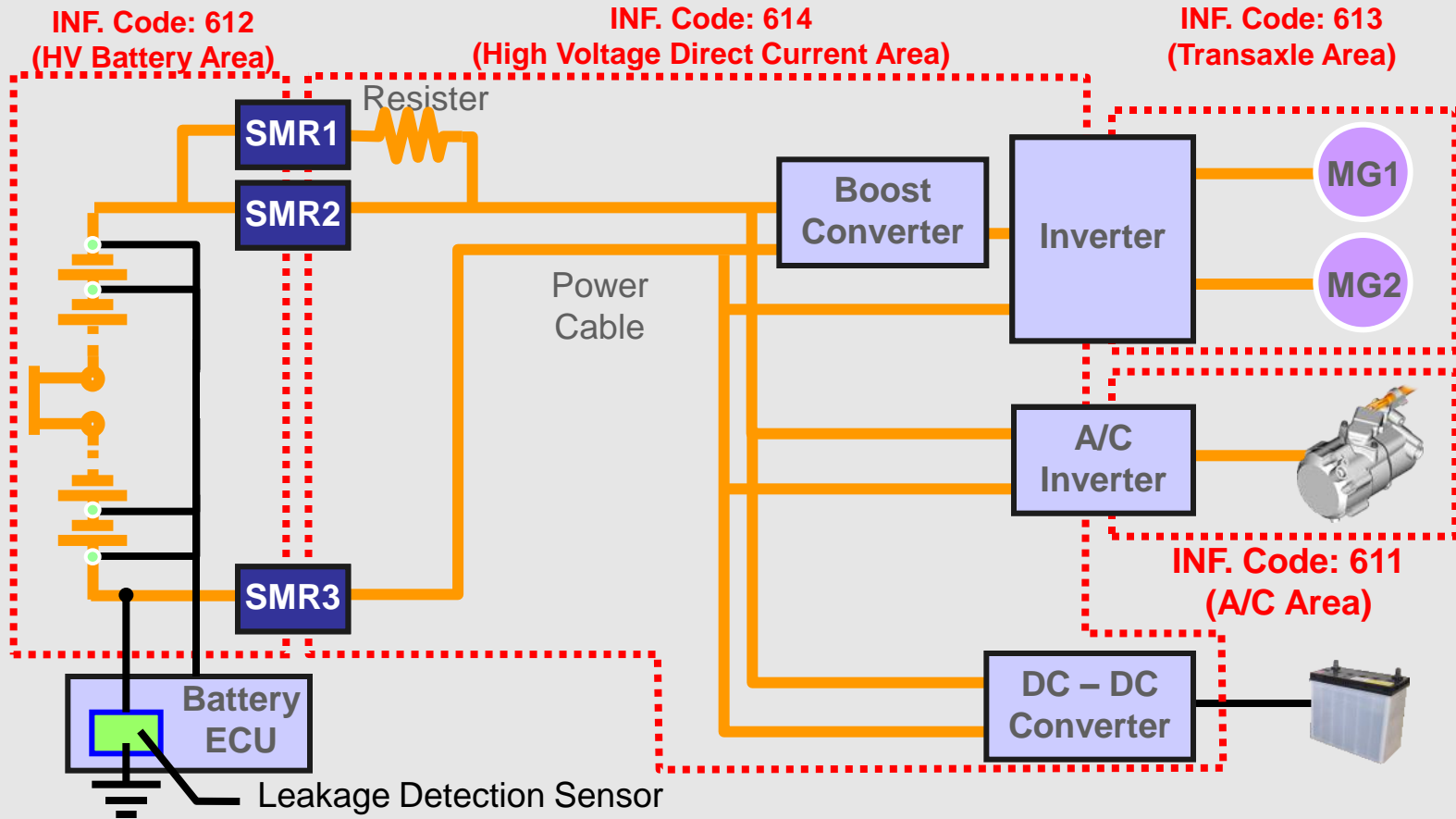
- System Diagram



# Leakage Detection High Voltage Circuit

- Detection Area

**Notice:** Detection area and malfunction portion is different



# Leakage Detection High Voltage Circuit

- Diagnosis

1. Electrical leakage detection at high-voltage circuit
2. Automatic determination of detection area



**Step1:** Electrical Leakage Detection -- [INF. Code 526]

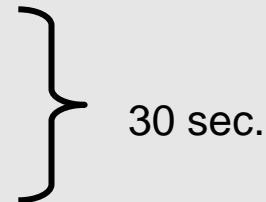
**Step2:** A/C OFF (at driving) ----- [INF. Code 611]

**Step3:** Power mode OFF (READY OFF)

**Step4:** Inverter (IGBT) OFF ----- [INF. Code 613]

**Step5:** SMR OFF ----- [INF. Code 612 or 614]

Don't turn OFF the power mode (10 sec.)



**Point!** It is necessary to wait for 30 sec. after power mode OFF to determine the detection area

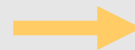
# Leakage Detection High Voltage Circuit

- Detection Logic

Model	Insulation Resistance		
	Threshold Value	Standard Value	Standard Value on Repair Manual
PRIUS	120 k $\Omega$	3.0 M $\Omega$	2 – 10 M $\Omega$  (value is different according to the measurement point)
RX400h	150 k $\Omega$	3.6 M $\Omega$	

10 sec. x 3 times in 1 Trip

Total 30 sec.



**Electrical Leakage Detection  
(INF. Code 526)**

**Notice:** Electrical leakage is not detected when the boost-up operation is performed

# Leakage Detection High Voltage Circuit

- Fail-safe

