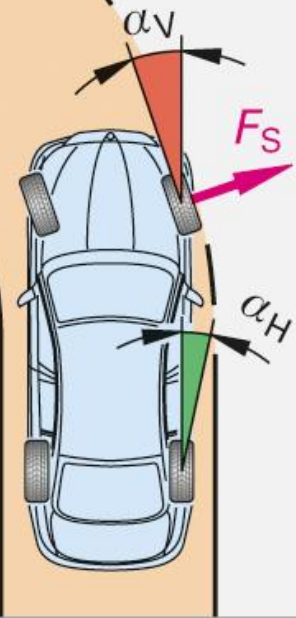
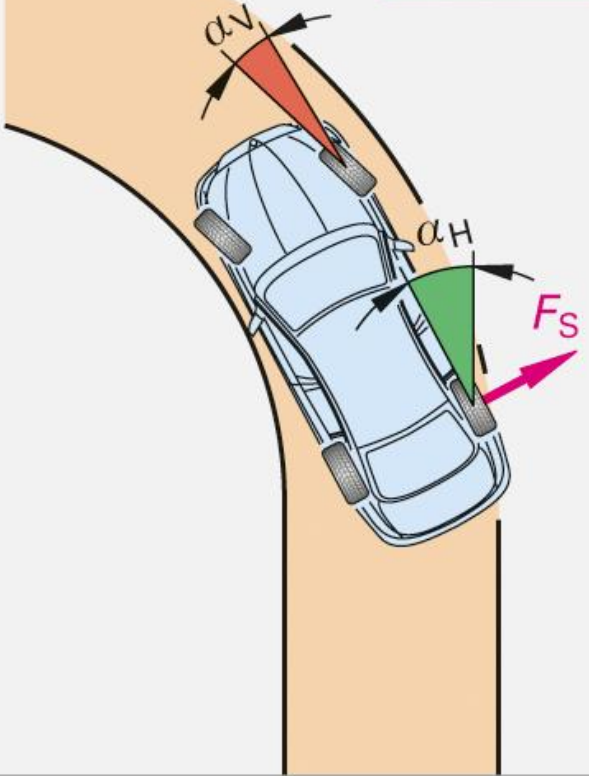
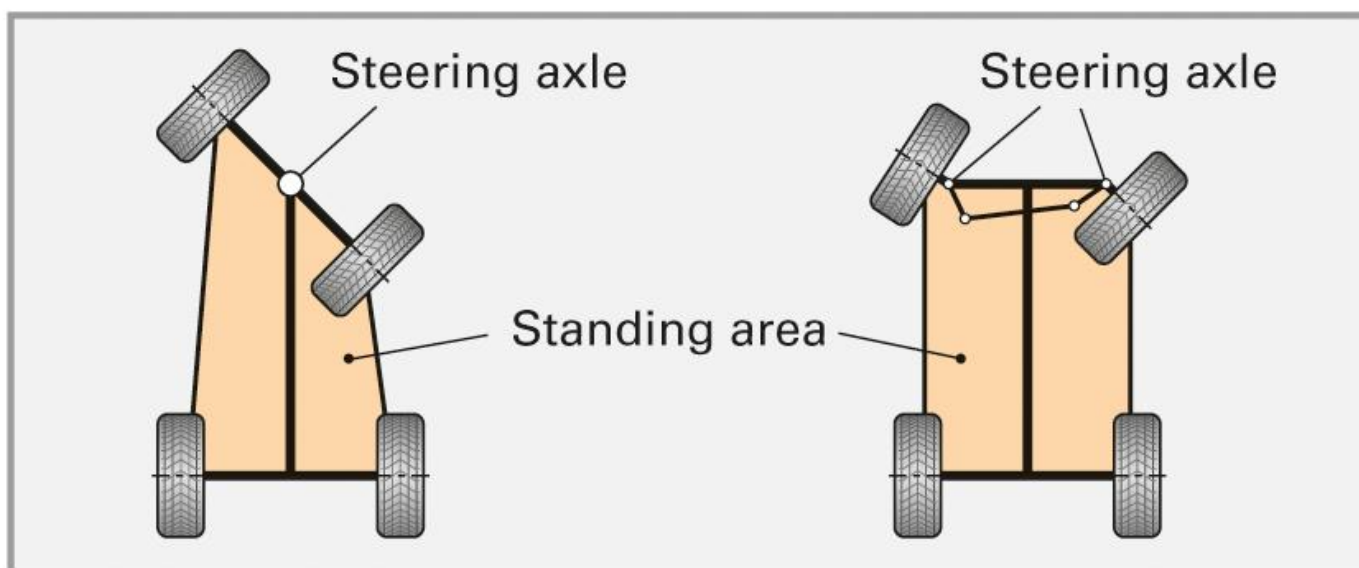
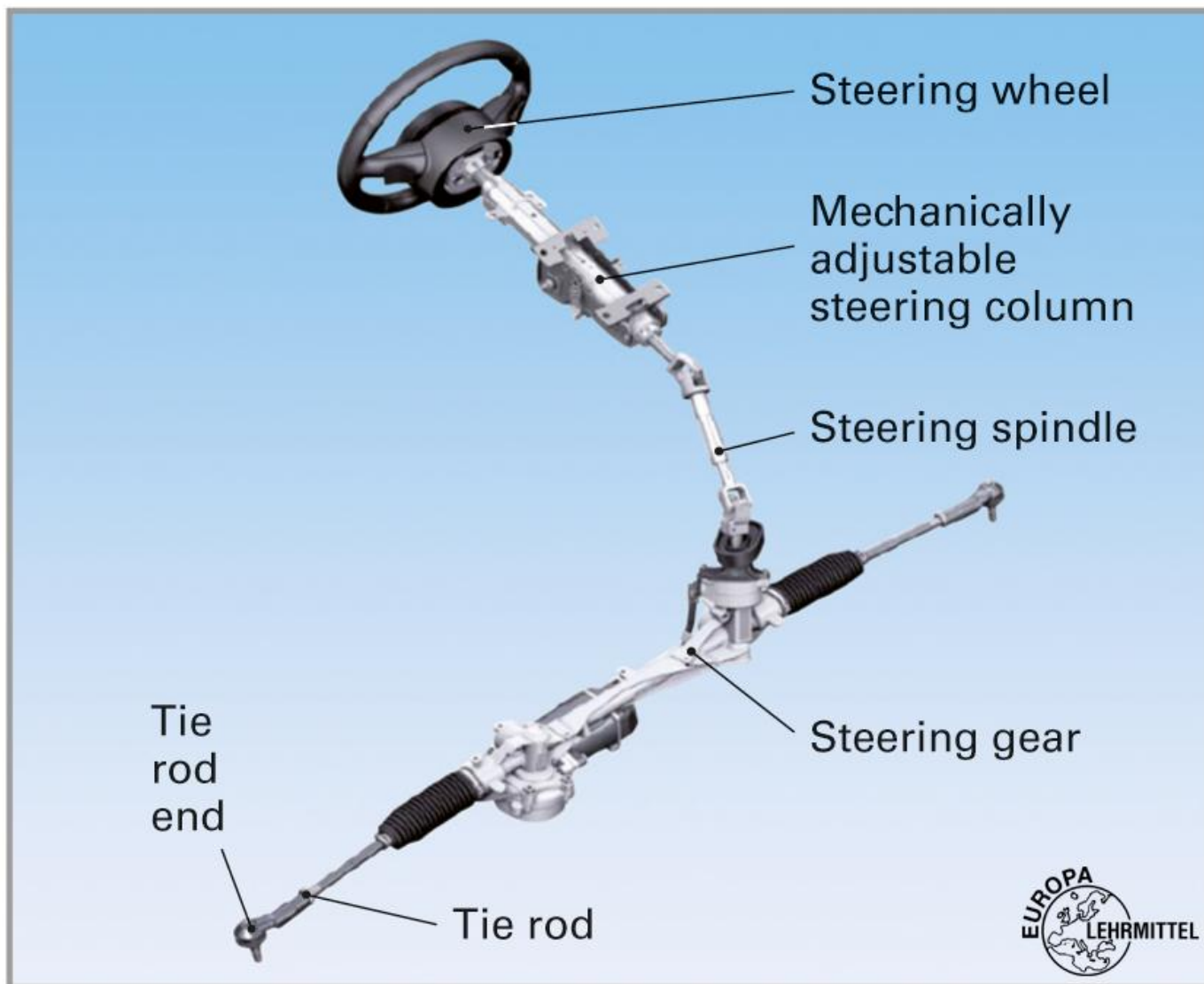


$$\alpha_V > \alpha_H$$

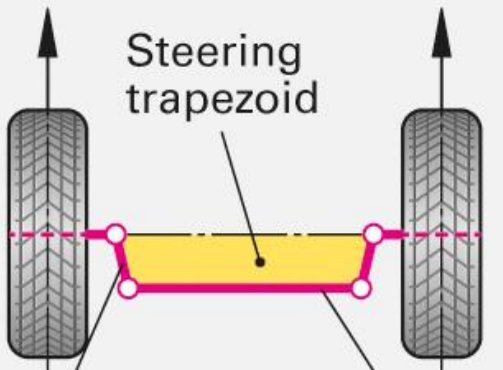
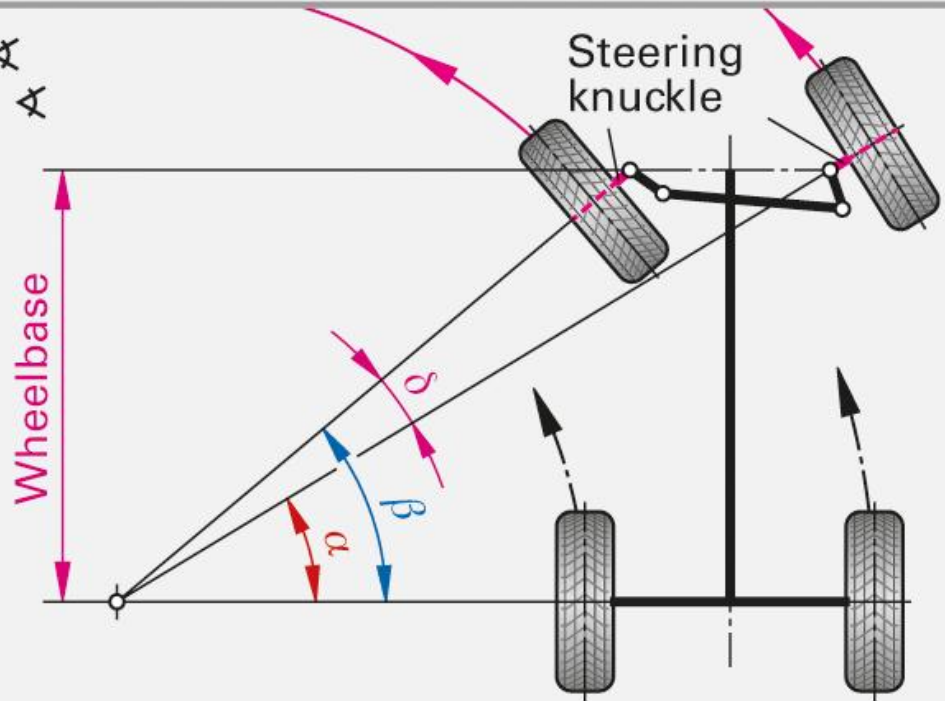


$$\alpha_H > \alpha_V$$

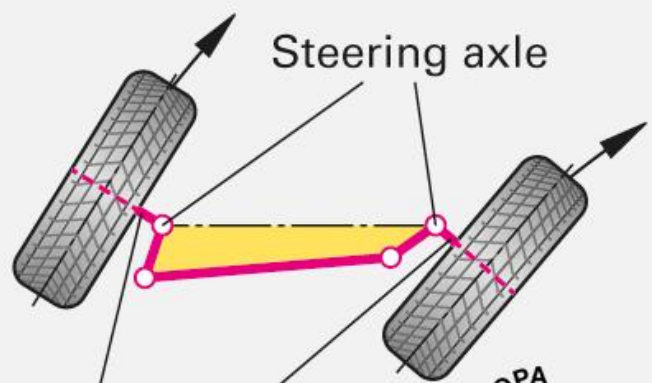




δ Toe difference \sphericalangle
 α, β Wheel angle \sphericalangle



Tie rod arm Tie rod



Steering knuckle



